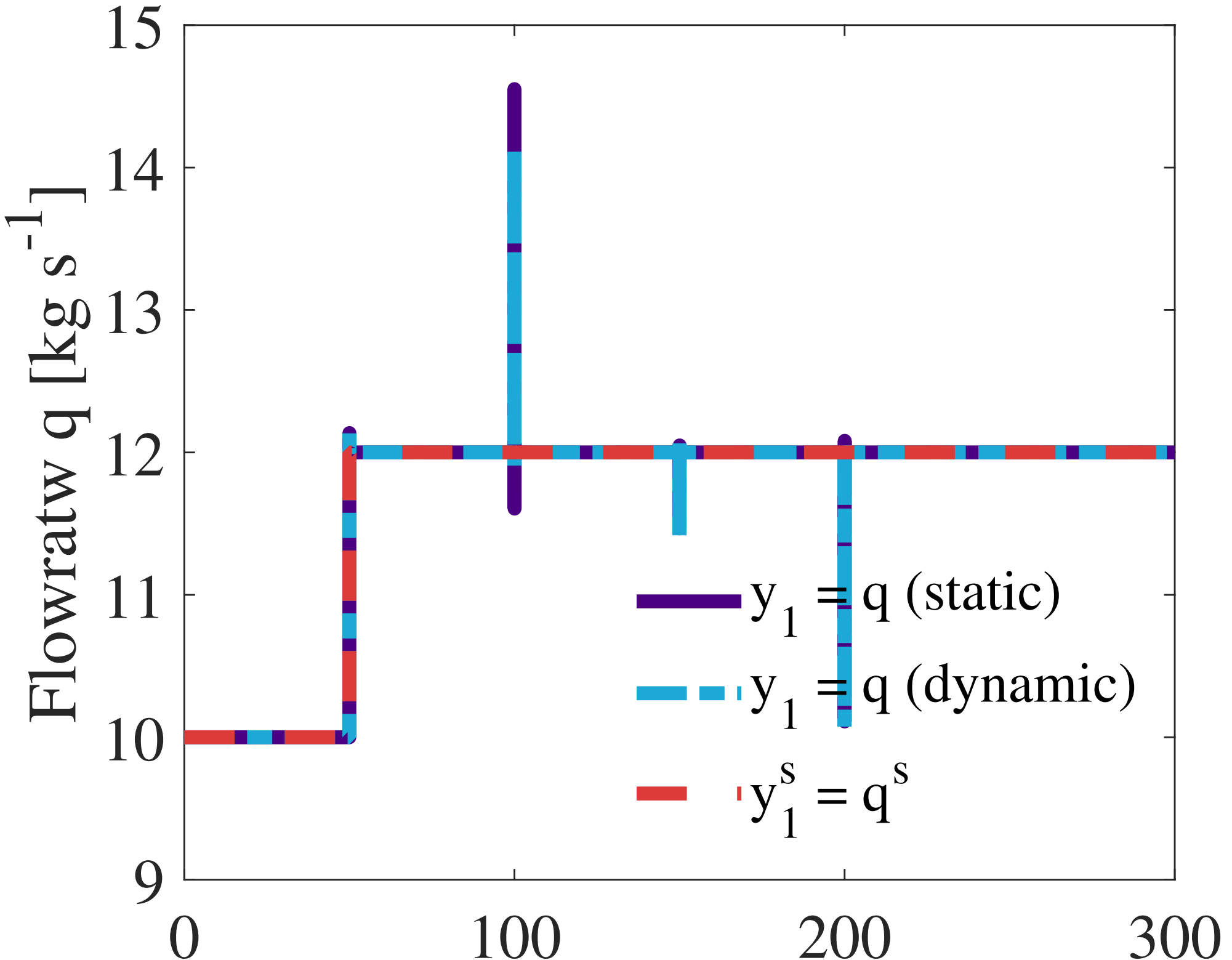
15
14
13
12
11
10
9
0
100
200
300
Flowratw q [kg s-1]
y1 = q (static)
y1 = q (dynamic)
y1s = qs