



**NTNU – Trondheim**  
Norwegian University of  
Science and Technology

# **Operatorless Processing Plants**

Status and challenges for autonomous control systems with focus on autonomous oil production.

Chriss Grimholt

7 December 2018

# Plan

- Introduction
- History
- The Modern Operator
  - Field
  - Startup
  - Monitoring
  - Production
- Final Thoughts

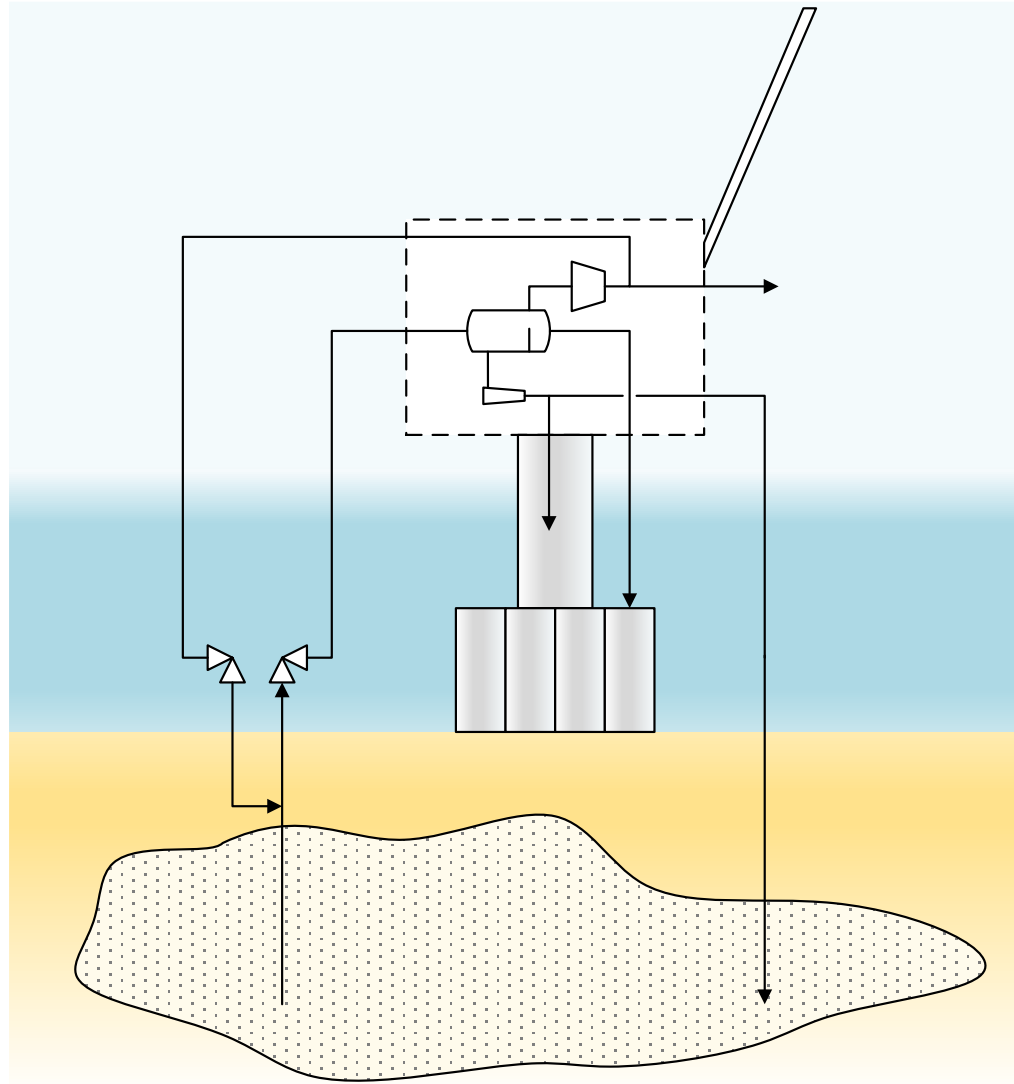
# Offshore Oil Production



ConocoPhillips - Ekofisk

Foto: ConocoPhillips

# Offshore Oil Production



# The Operator

*Probably the most famous operator in the world (though not very good)!*

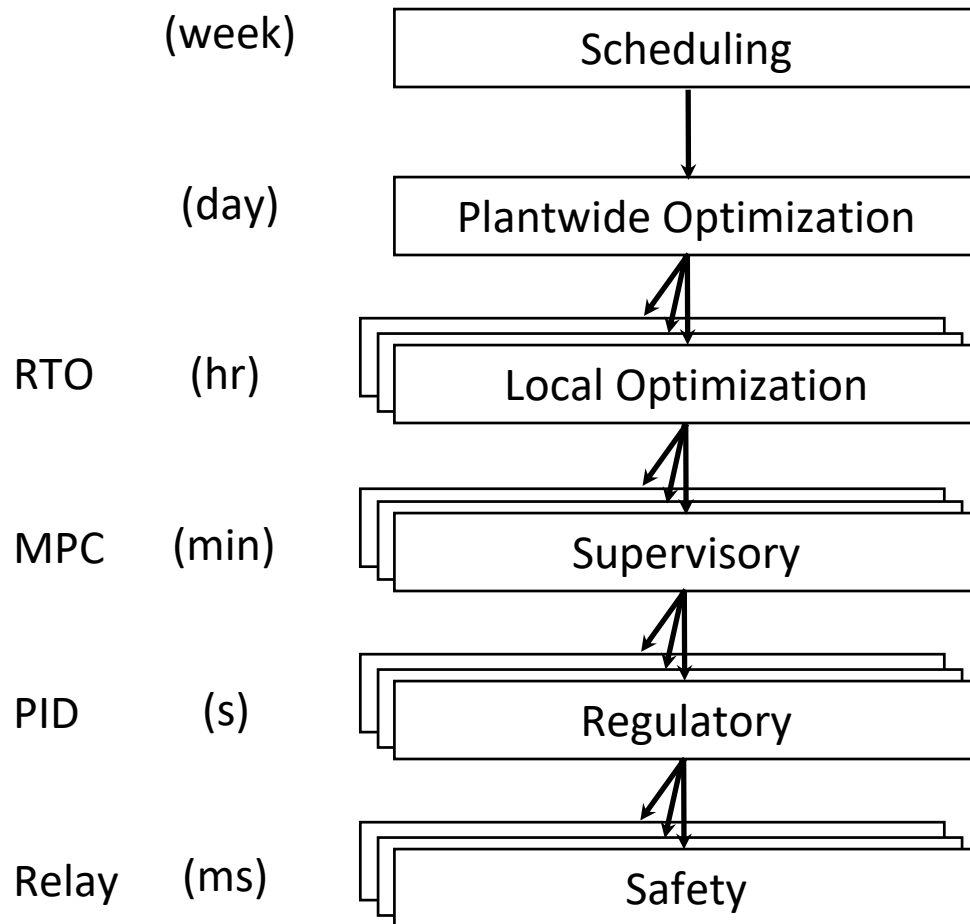


# The Operator

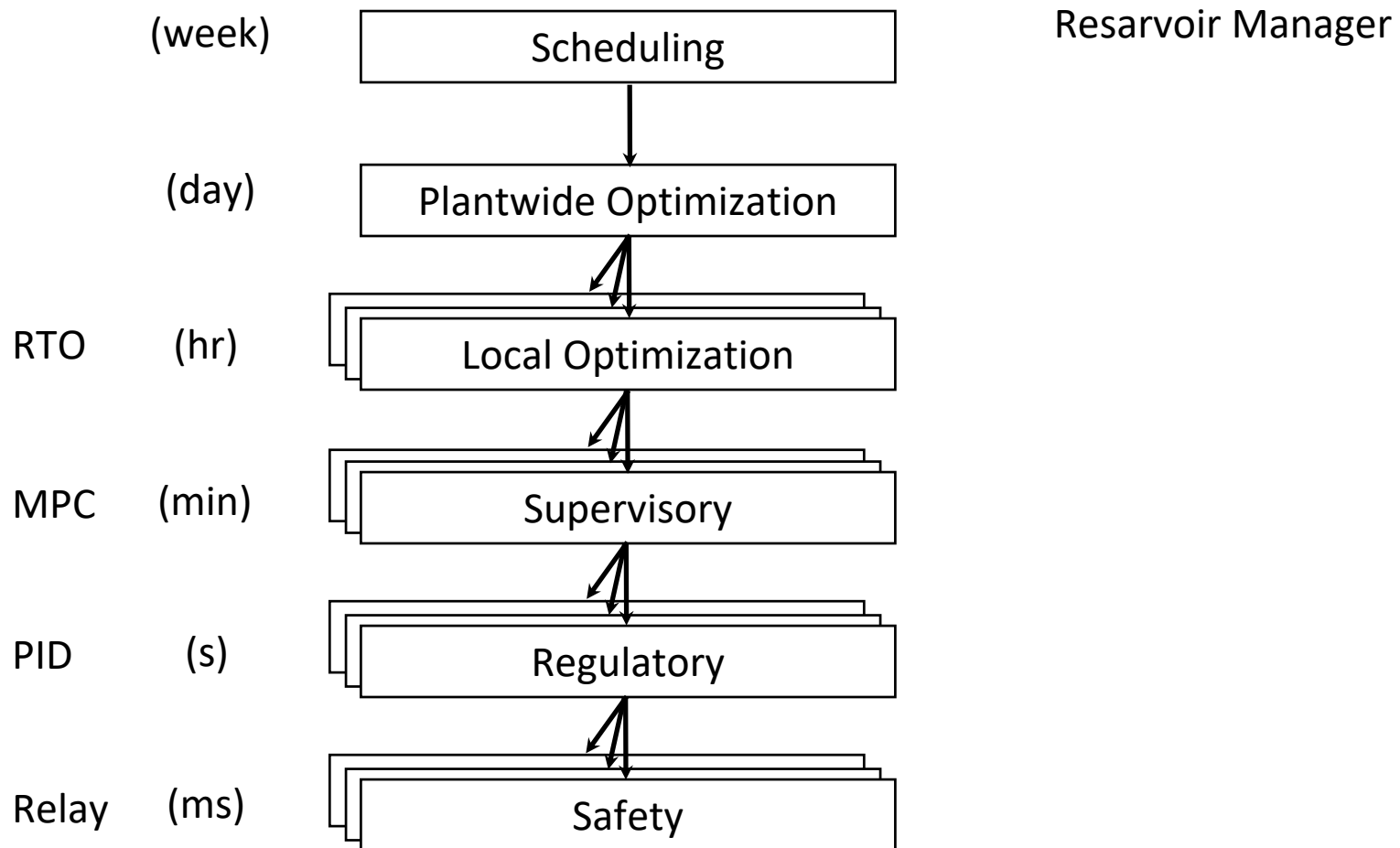
*The operator monitors the process and does what is in his power to keep the plant running in a safe manner.*

- Starts and stops the plant
- Detects and corrects for faults
- Tries to get the correct product quality
- ...

# Decision Hierarchy

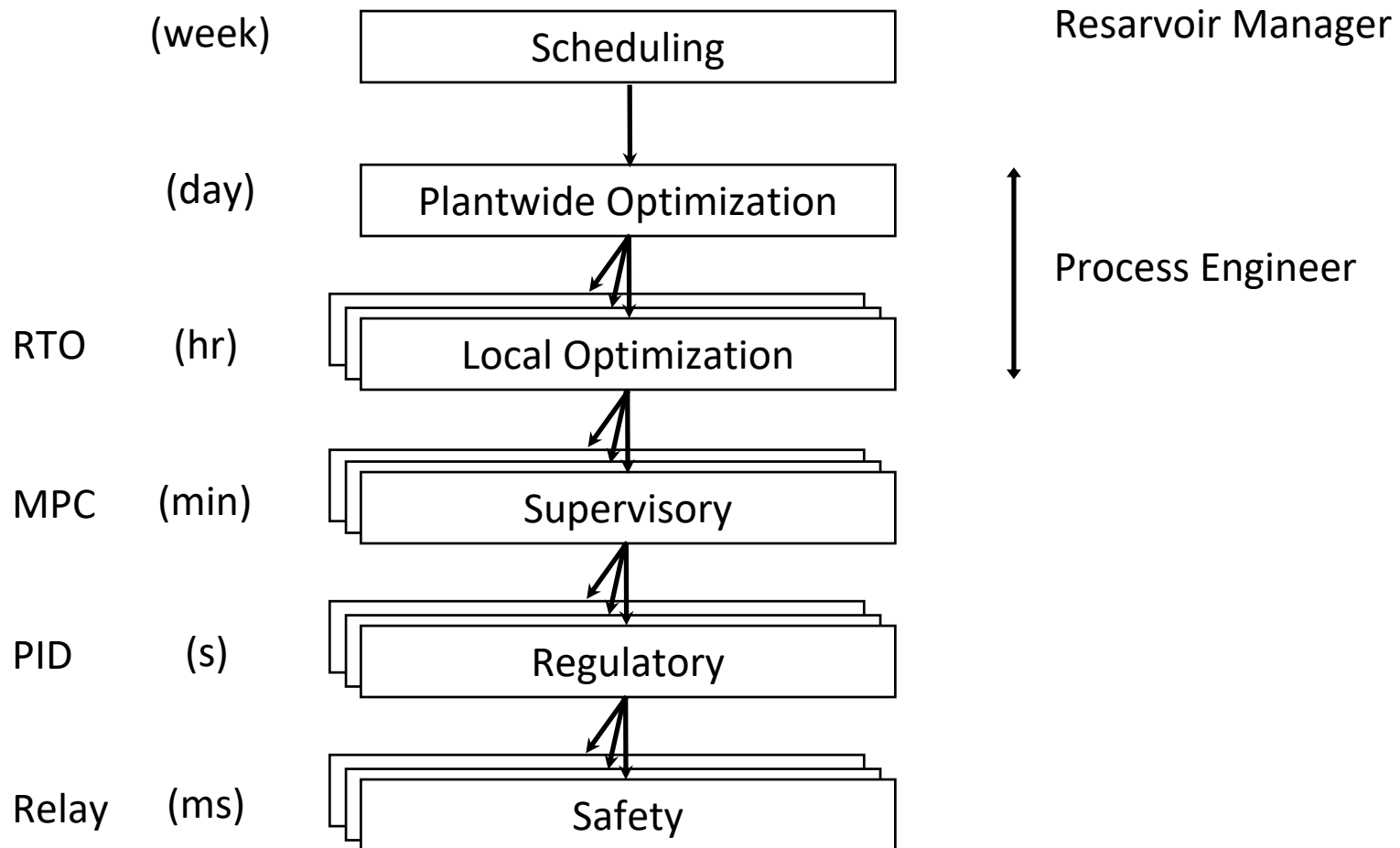


# Decision Hierarchy

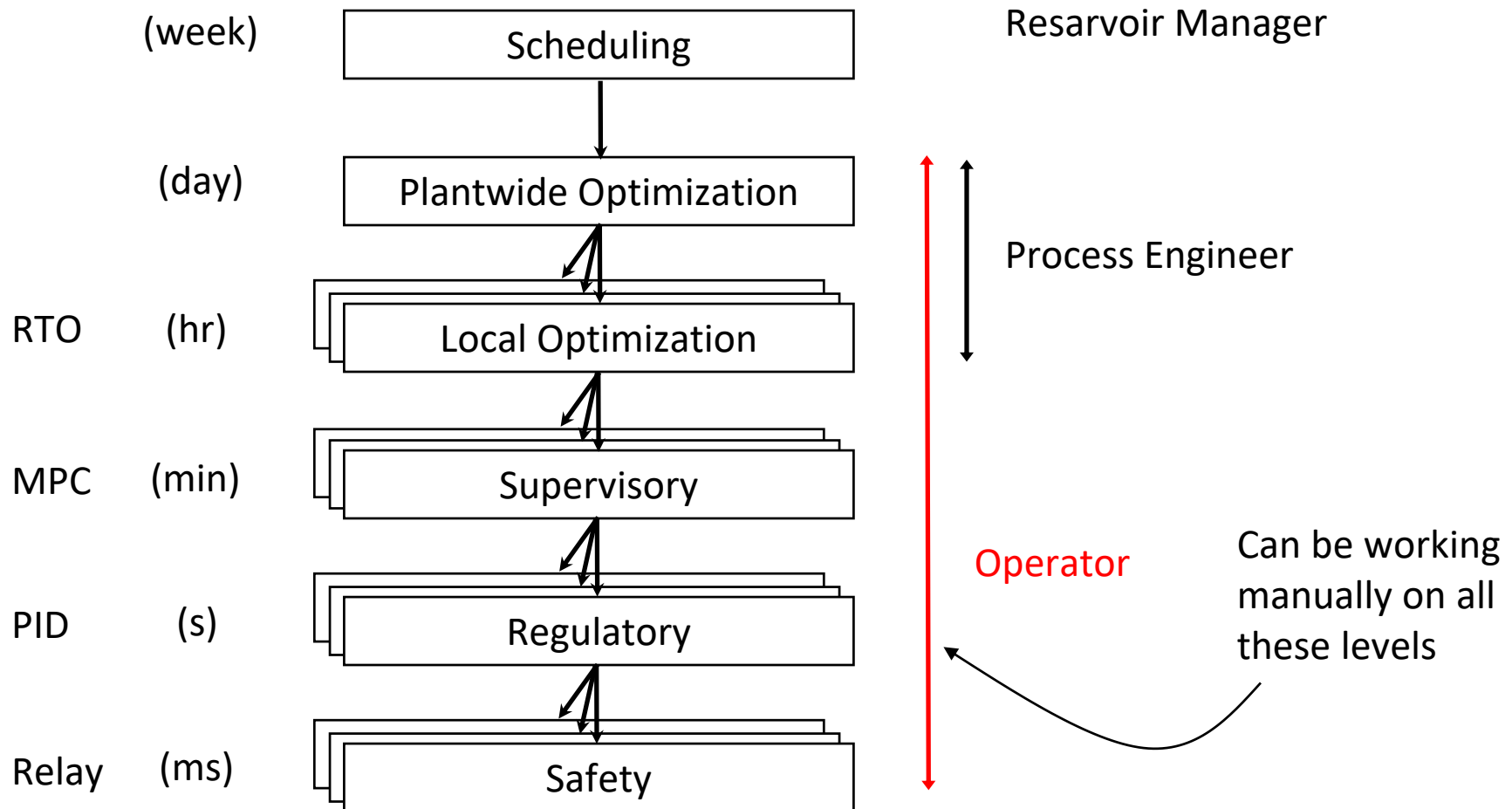




# Decision Hierarchy



# Decision Hierarchy



# Autonomous

*"A system is autonomous if it can solve its task without external intervention"*

Wallén, Anders (2000). Tools for Autonomous Process Control. PhD Thesis, Department of Automatic Control, Lund Institute of Technology (LTH)

# Autonomous

*"A system is autonomous if it can solve its task without external intervention"*

Elevator:

You give a command,  
The elevator takes you there

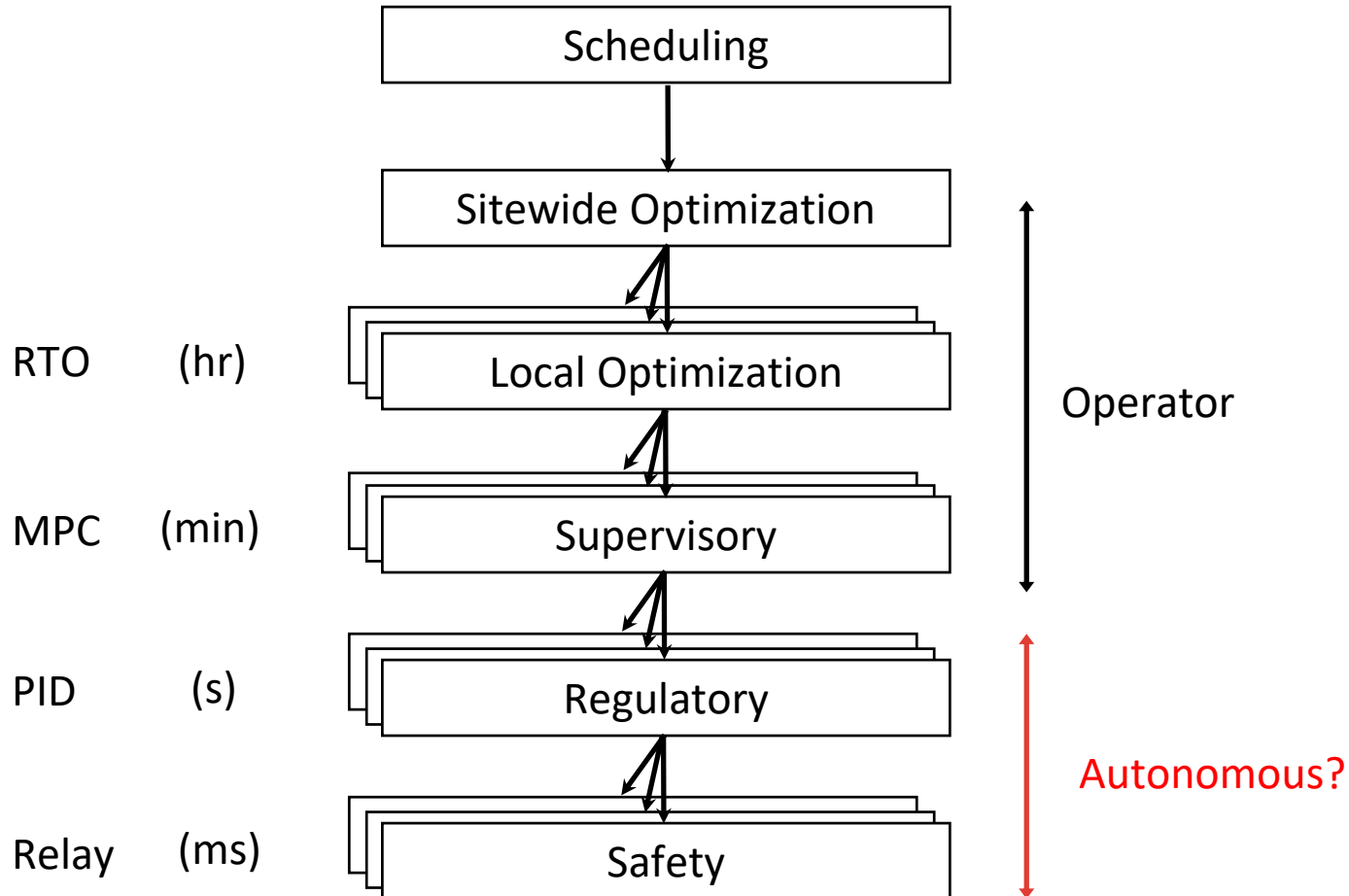


Can be said to be autonomous

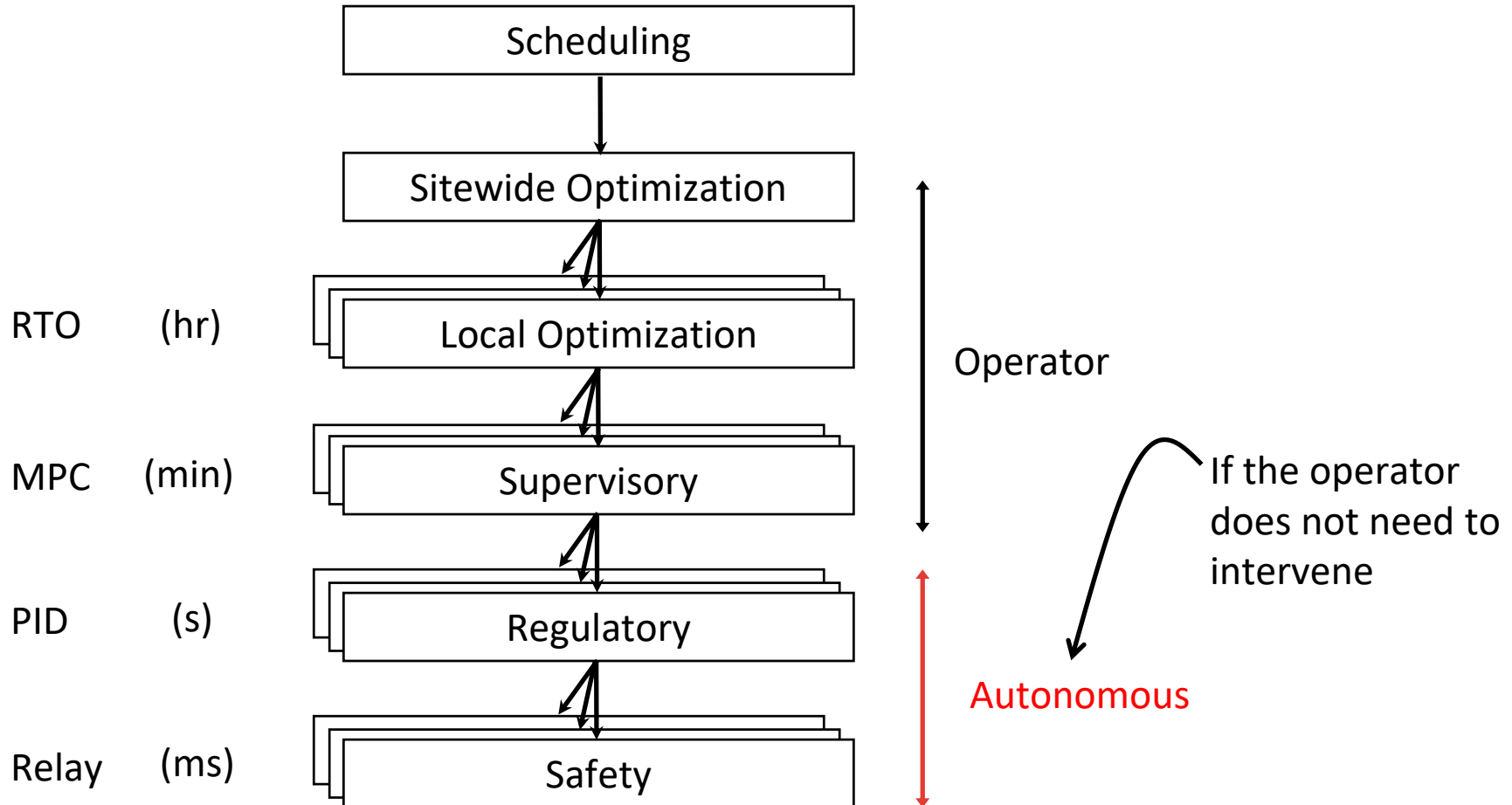
However, no system is autonomous under all circumstances.  
E.g. Power loss, measurement loss, someone standing in the doorway.

Wallén, Anders (2000). Tools for Autonomous Process Control. PhD Thesis, Department of Automatic Control, Lund Institute of Technology (LTH)

# Is it Autonomous?



# Is it Autonomous?



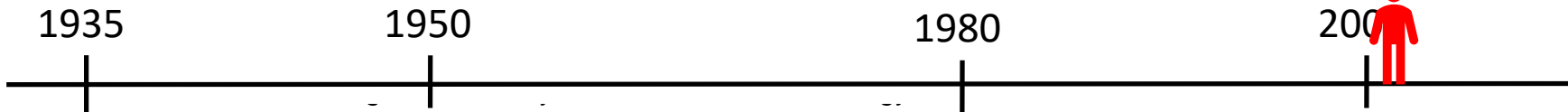
# History of Jahre and Operators (simplified)



Jahres Fabrikker

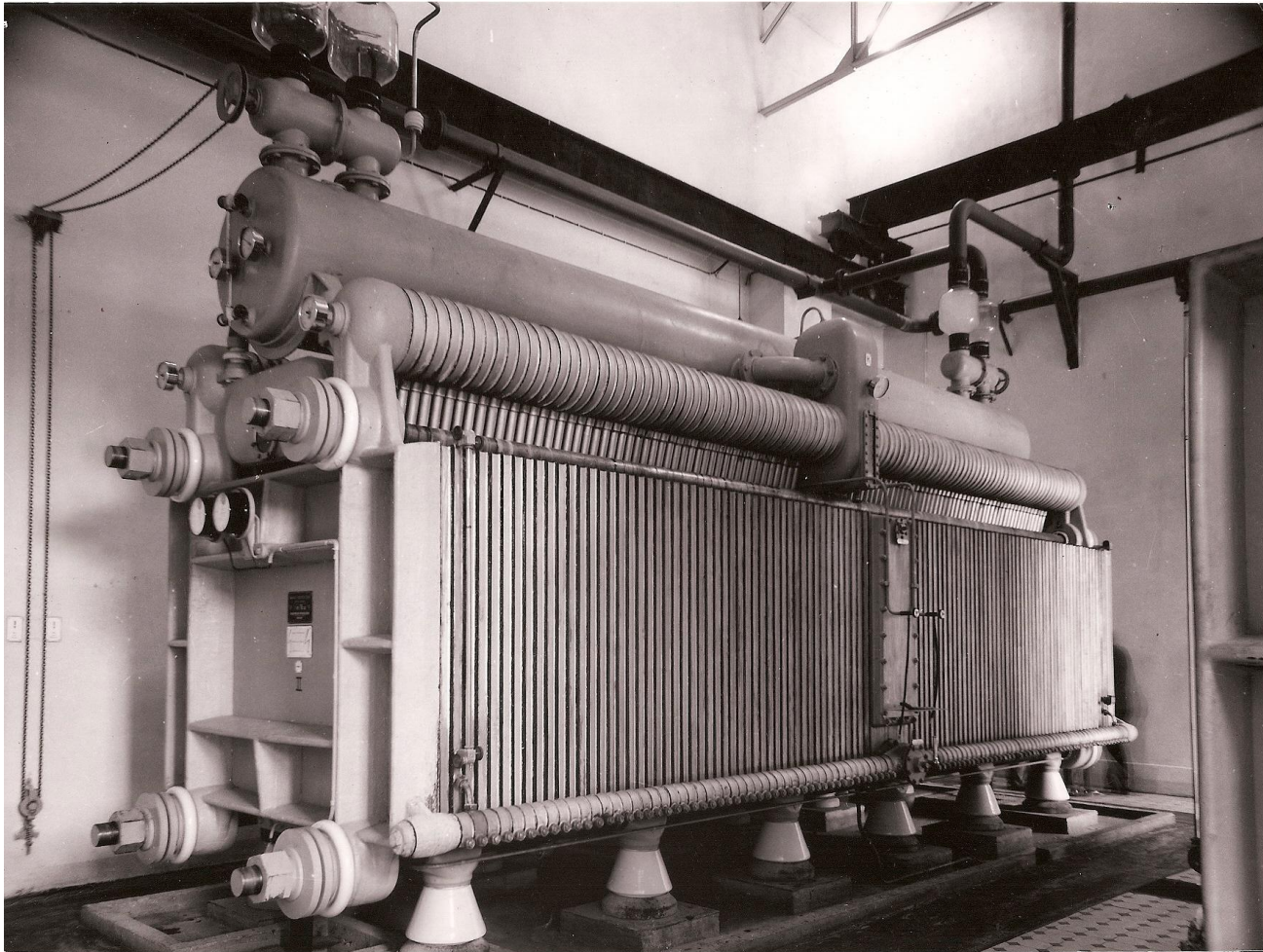
Tore Gjone Møller

1955 Kokerteri Gonvika





# 1930s



1935 Elektrolyser 3 Bamag

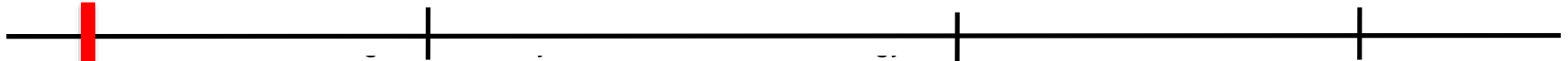
Tore Gjone Møller

1935

1950

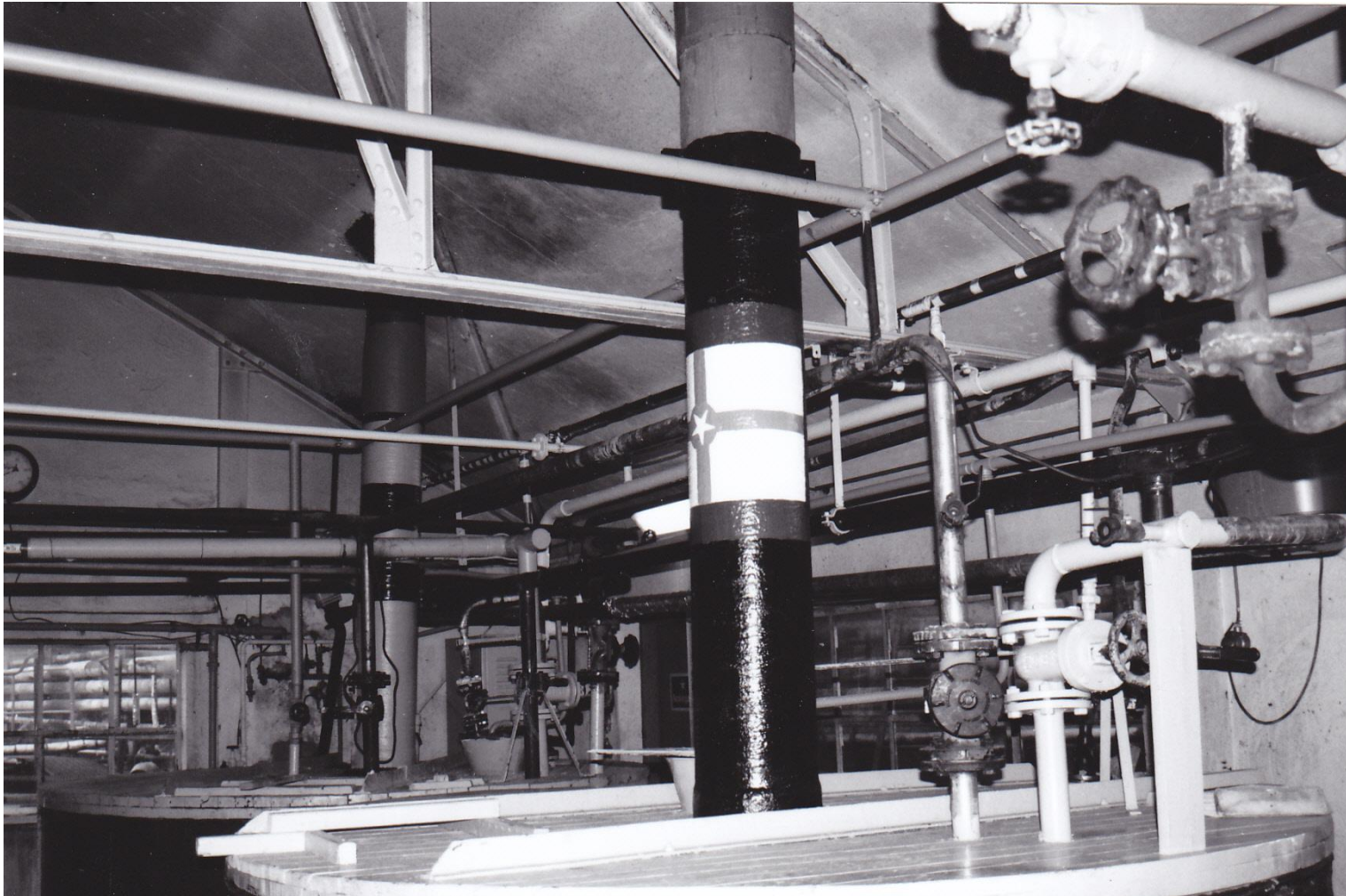
1980

2000





# 1930s



Tore Gjone Møller

1935

1950

1980

2000

# Example of Manual Control (not 1930s)



Sandefjord Lokalhistoriske Senter og Sandefjord bibliotek  
Bildet må ikke brukes uten tillatelse fra rettighetshaver.

Oleon Scandinavia

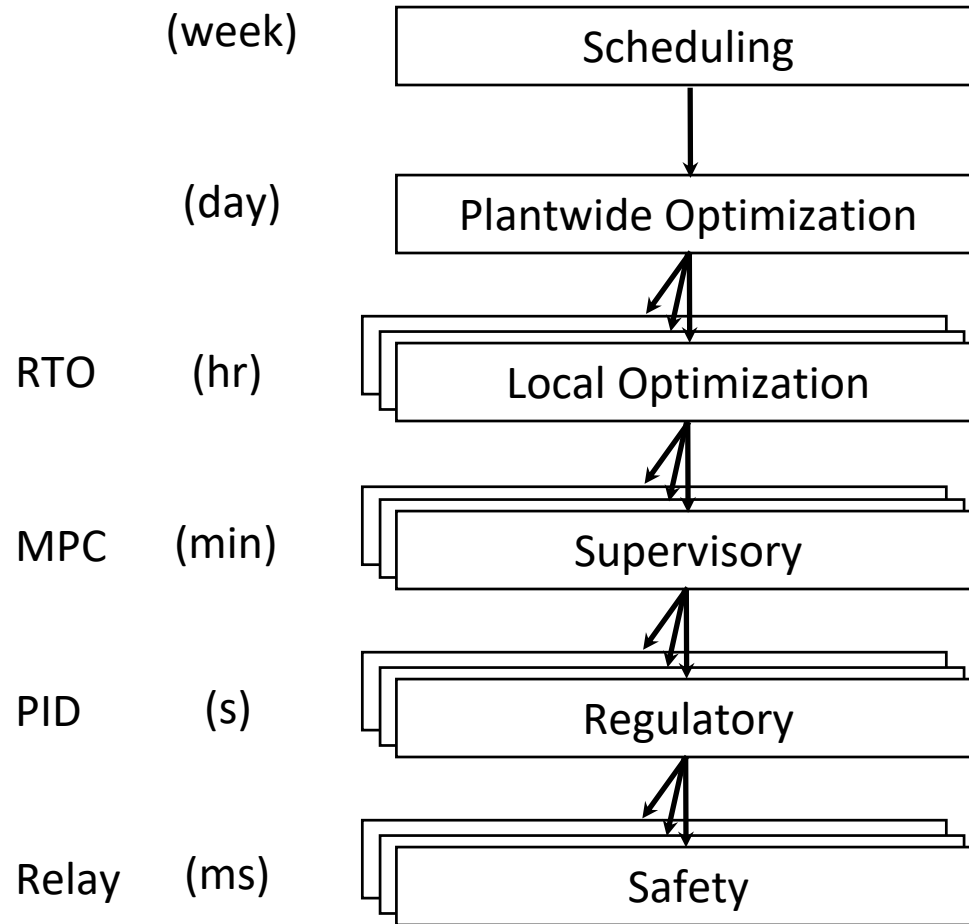
1935

1950

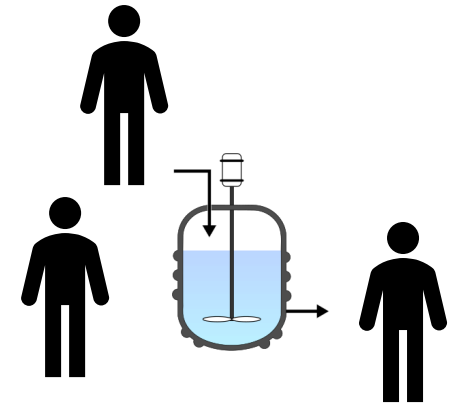
1980

2000

# Manual Control



- Mechanical measurements distributed in the processing unit
- Some primitive mechanical control



Operator

1935

1950

1980

2000



# 1950s



Tore Gjone Møller

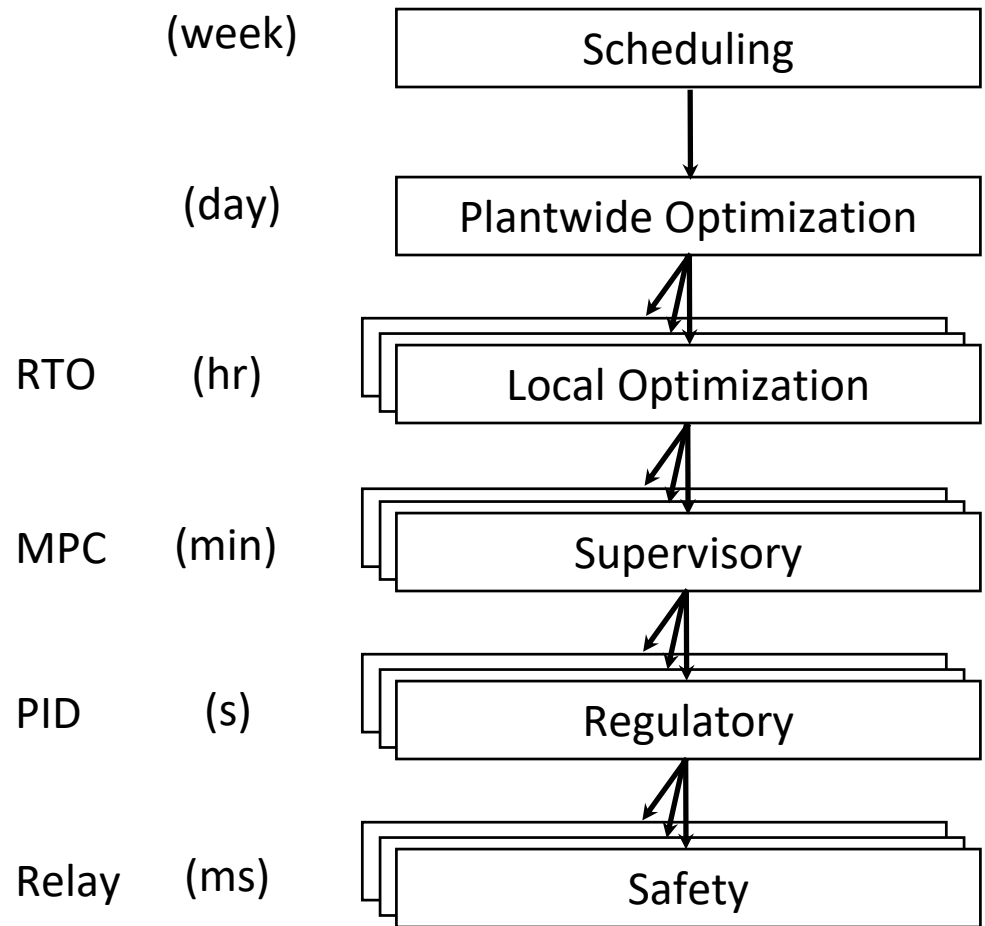
1935

1950

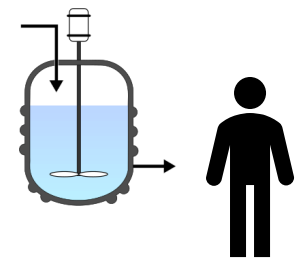
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2000

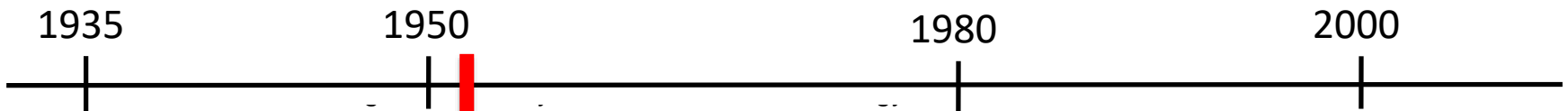
# Pneumatic and control rooms



- The first control room
- A few alarms



Operator



# 1980s



Tore Gjone Møller

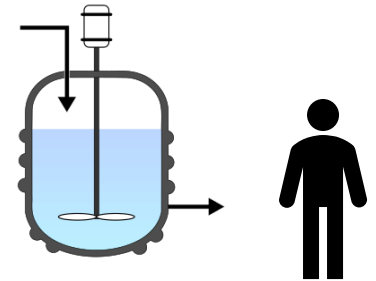
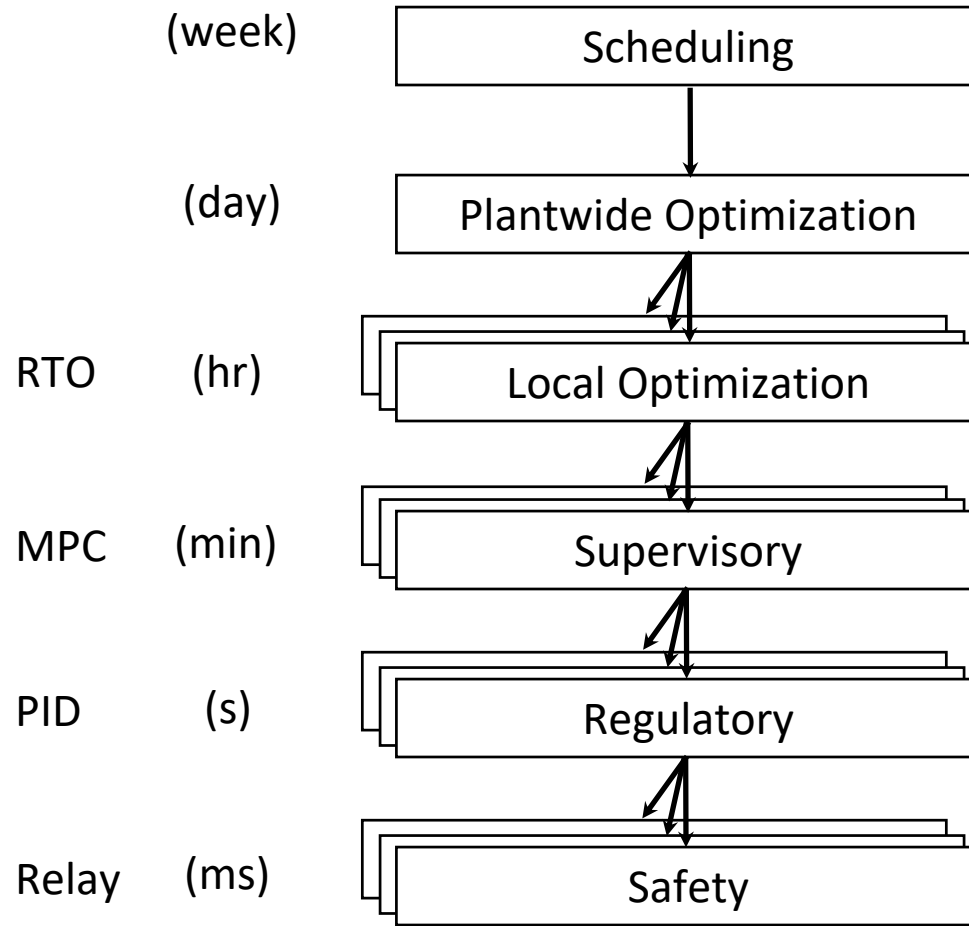
1935

1950

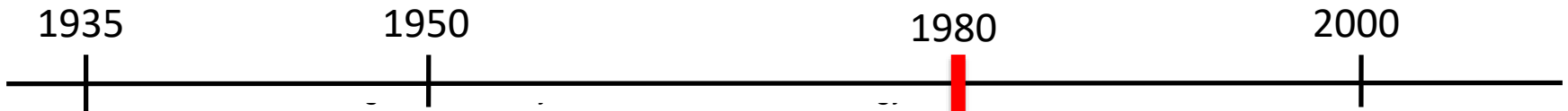
1980

2000

# Electric Control



Operator



# 1990s



1935

1950

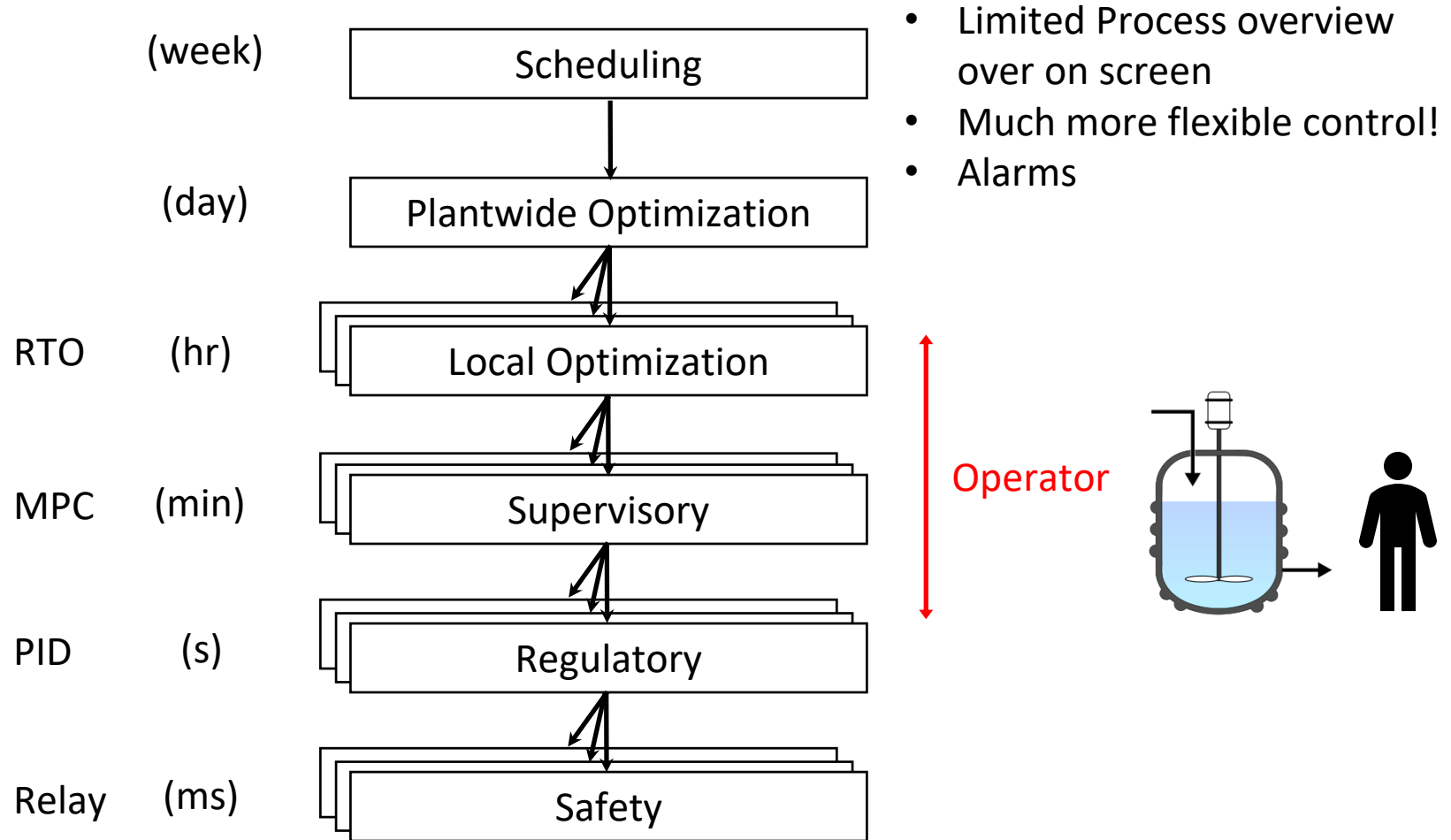
1980

2000





# Distributed Control Systems



- Limited Process overview over on screen
- Much more flexible control!
- Alarms



# 2000s



<http://www.abb.com/cawp/seitp202/8583b3ebb6422b9ac1257eab001d38d9.aspx>

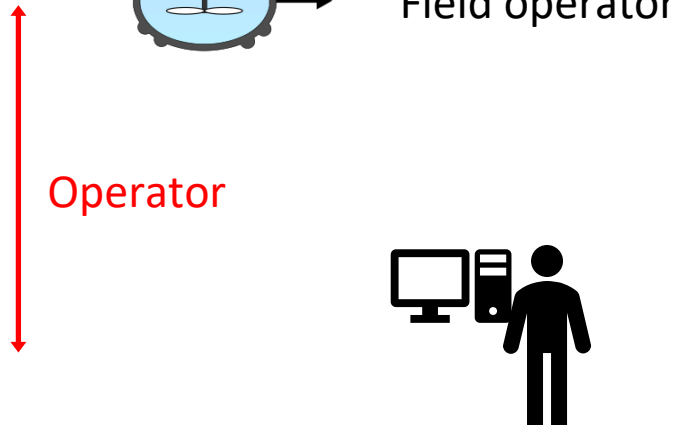
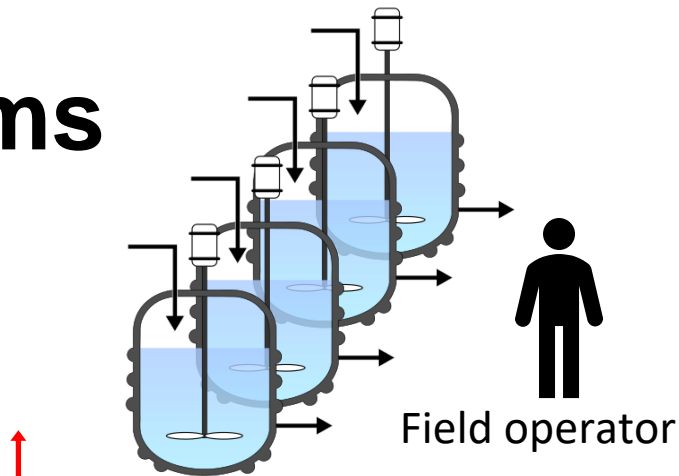
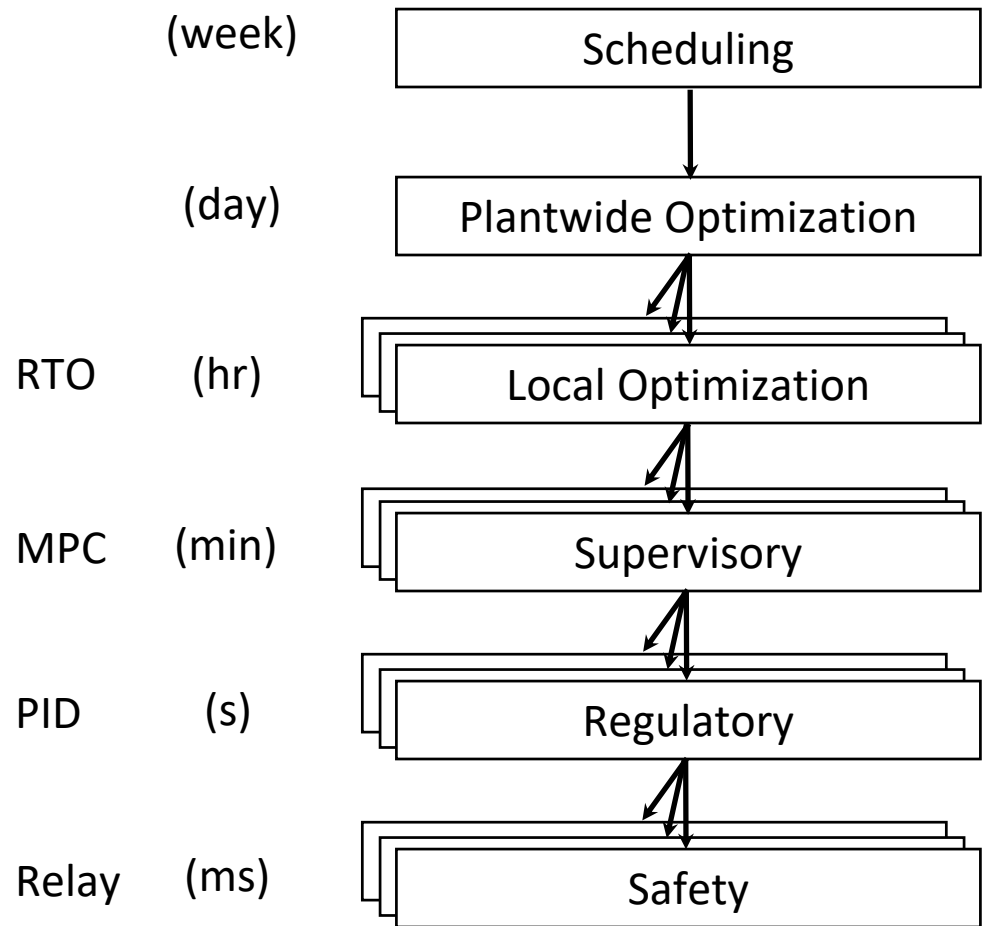
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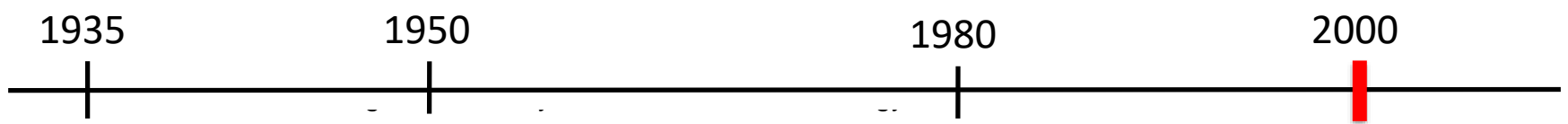
2000

# Centralized Control Rooms



Operator

Control room operator



# What Does the Modern Operator Do?

## Field operations

- Operating manual valves
- Prepare for maintenance
- Sample taking/analyze quality
- Validating measurements
- Inspections rounds:  
visual, smells, vibration, sounds, temperature

## Startup operations

- Startup and shutdown of plant
- Procedural operations like changing pumps, pigging, etc.

## Monitoring operations

- Fault detection and correction
- Validating measurements
- Intervene when the plant is approaching some safety limit

## Production operations

- Handling bottlenecks
- Backing off from constraints
- Controlling quality

# What Does the Modern Operator Do?

## Field operations

- Operating manual valves
- Prepare for maintenance
- Sample taking/analyze quality

What do you think is the hardest to automate?

inspections rounds:  
visual, smells, vibration, sounds, temperature

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# Unmanned Offshore Oil Production



## **Equinor - Oseberg H**

The first unmanned wellhead platform on the Norwegian continental shelf.

First production Oct 2018

## **Equinor - Peon (in planning)**

The first unmanned production platform.

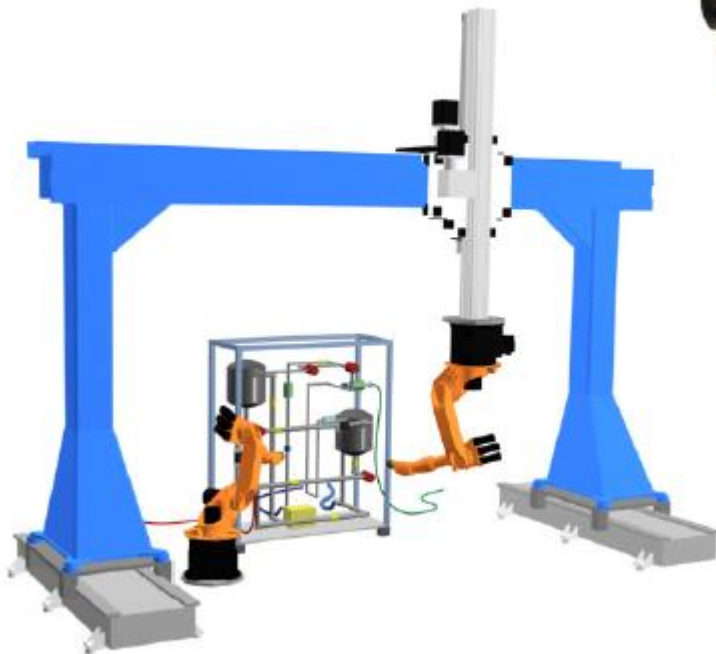
Oseberg H. Photographer: Erlend Hatteberg / CHC Helikopter Service / © Equinor



# Outdoor Operator

## Inspections rounds

- leaks
- smells
- vibration
- sounds
- temperature



■ Laser Vibrometer



■ Temperature/vibration sensor



■ 3D Camera



■ Valve Operation Tool



■ Gripper



■ Tool exchange system



■ Battery Exchange Tool



R2D2

Erik Kyrkjebø, Pål Liljebäck, Aksel A. Transeth (2009). Robotic concept for remote inspection and maintenance on oil platforms. Proceedings of the ASME 2009 28th International Conference on Ocean, Offshore and Arctic Engineering, OMAE2009-79702



# What Does the Modern Operator Do?

## Field operations

- Operating manual valves
- Prepare for maintenance
- Sample taking/analyze quality
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## Startup operations

- Startup and shutdown of plant
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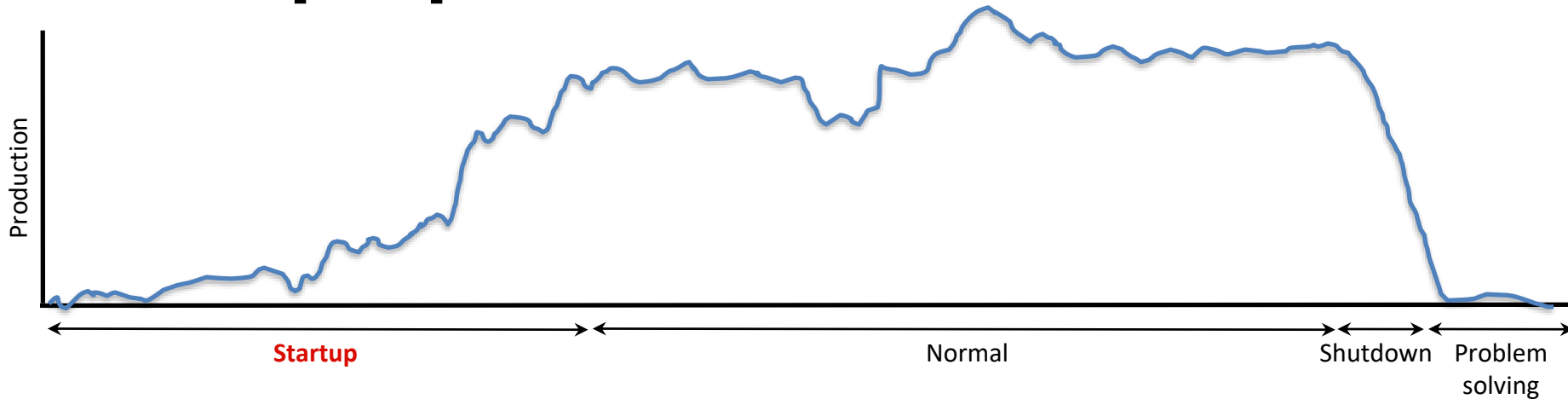
## Monitoring operations

- Fault detection and correction
- Validating measurements
- Intervene when the plant is approaching some safety limit

## Production operations

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# Startup Operations



Scheduling

Sitewide Optimization

Local Optimization

Supervisory

Regulatory

Safety

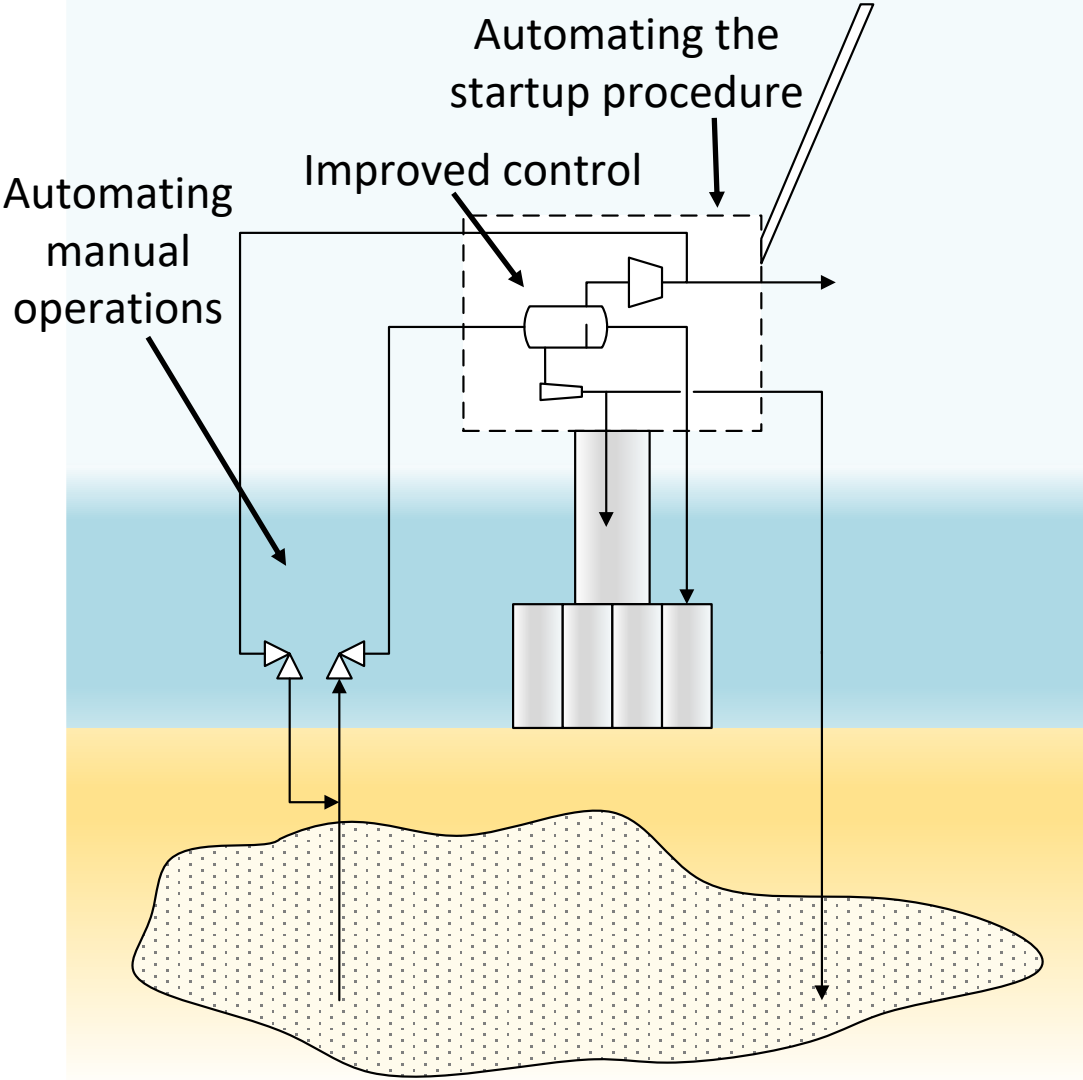


Operator

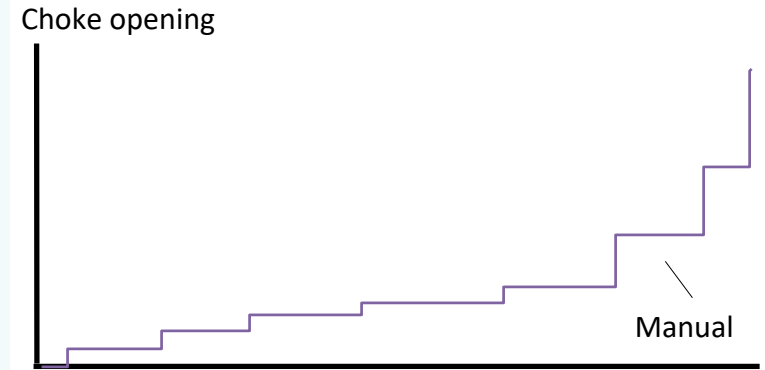
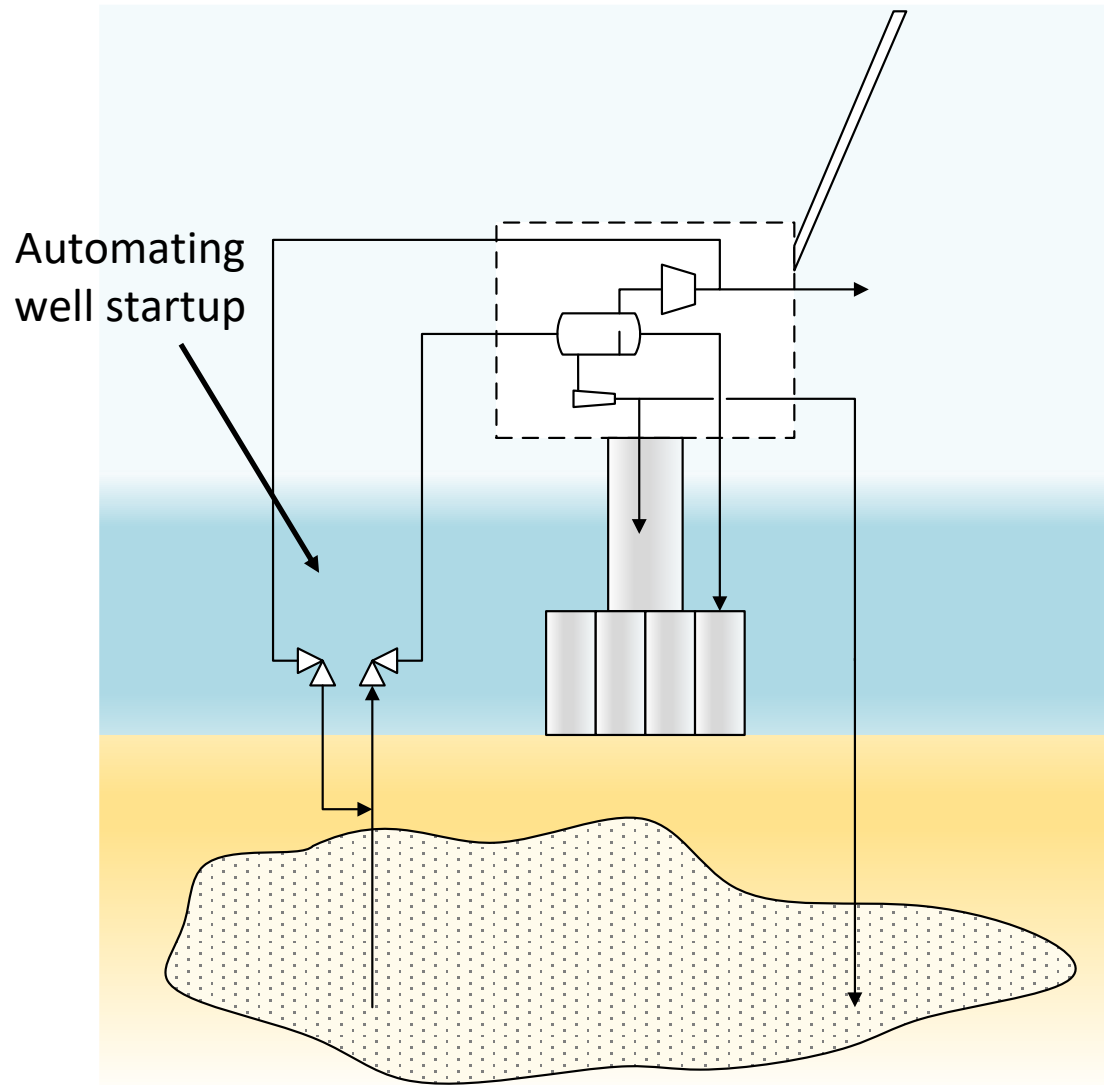
How can we push the operator up?



# Three Main Challenges



# Manuell well startup



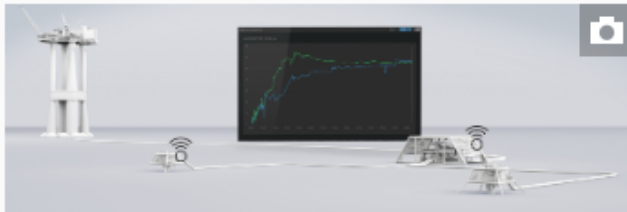
Example of well startup strategies

# Automated Well Startup



HOME → OFFERINGS → ABB OIL AND GAS → DIGITAL → SMART WELL

GLOBAL SITE



## Automized Well Ramp-up

Wells are normally ramped up manually in a conservative way to protect the integrity of the well during periodic integrity testing and other planned/unplanned shutdowns. The result of this is a hidden production loss since the wells can be ramped up faster by using an automized approach still keeping the well integrity in a safe range.

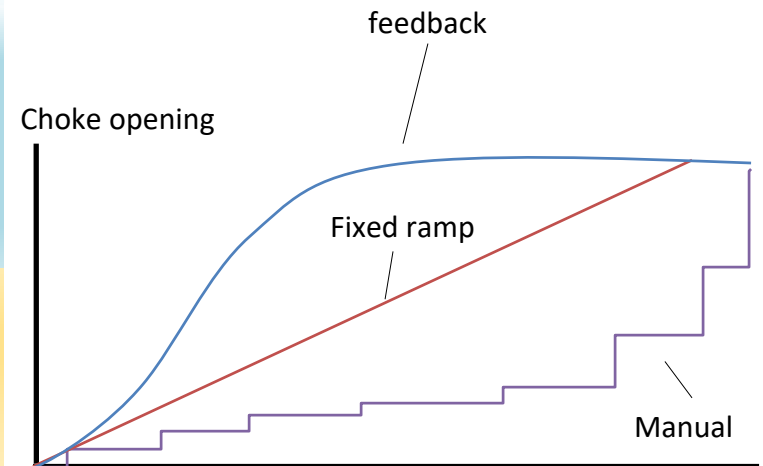
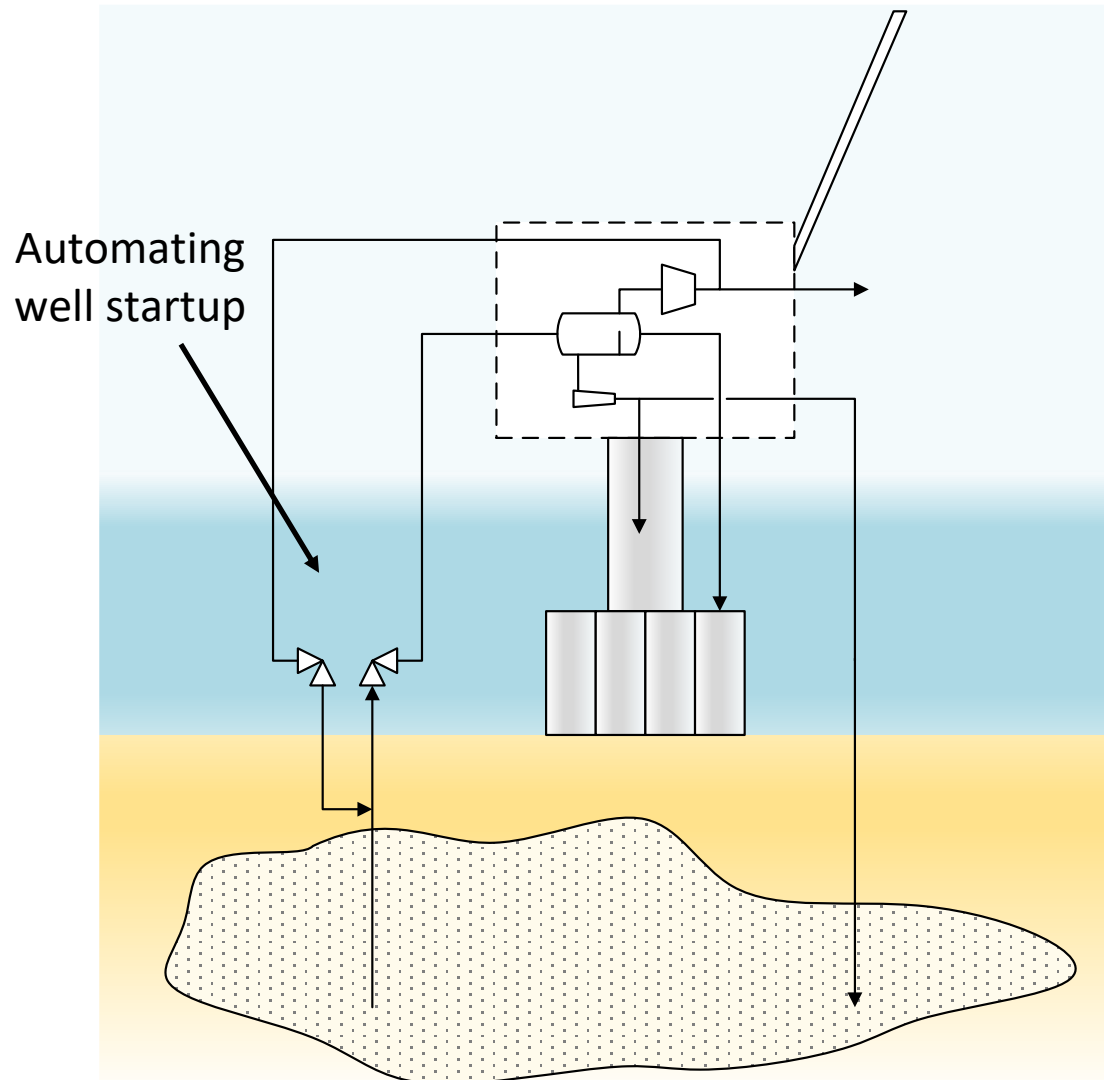
### Our solutions

With Automized Well Ramp-up, operators are able to speed up the process and increase production. By monitoring and controlling critical variables in all the wells during ramp-up, and knowing what is happening in the well's process dynamics, the speed of the ramp-up is adjusted accordingly.

For example, there are 16 wells in production at Ormen Lange in the North Sea. Each well extends 2000 meters below the seabed and is surrounded by gravel and sand. Previously, it typically took 9 hours to ramp up a low pressure well and 15-20 hours for a high pressure well. The process was safe, but it did not take into account what was happening in the wells in real time. After installation of ABB's solution, the wells can now be opened much faster than before and with reduced risk to well integrity and safety. On average, it now takes only 2 hours to open low pressure wells and 6 hours to open high pressure wells.

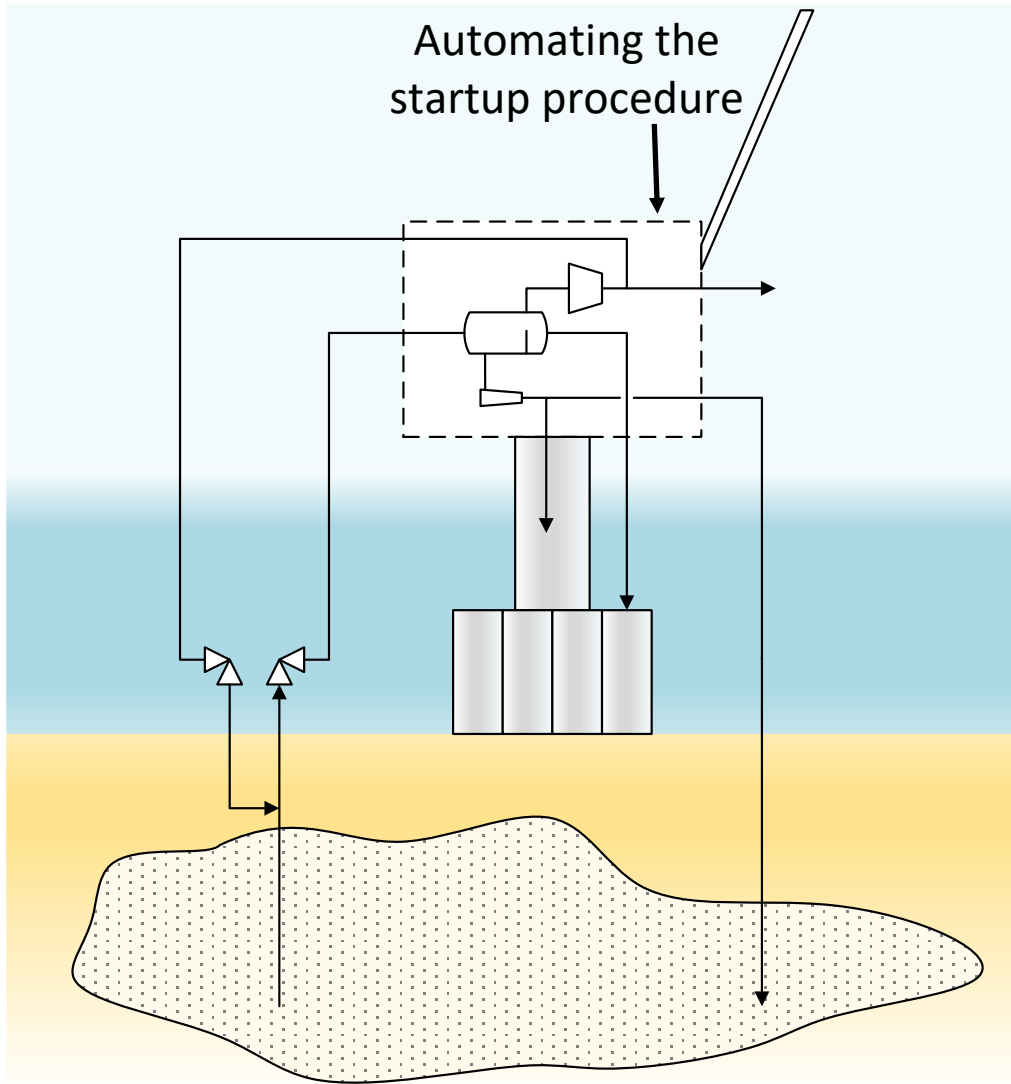
<https://new.abb.com/oil-and-gas/digital/smart-well>

# Automated Well Startup – just feedback



Example of well startup strategies

# Manual Startup Procedure



# Examples of automatic startup of plant

## ABB to deliver fast upstream start-up for Aasta Hansteen's first gas production

August 27, 2018, Oslo, Norway – Ability™ technology estimated to save 40 days in commissioning phase by reducing manual interventions by 98 percent

ABB is not alone in delivering what it believes to be the world's fastest start-up when Equinor's operating and produces its first gas later this year.

ing a suite of innovative ABB Ability™ digital which is located in 1300 meters of water in the Vøring kilometers from land.

s to make the first gas start-up process as quick and B needed to reduce a sequence of over 1000 manual e. The outcome is a series of buttons that are as simple

t-up steps, identified and defined obstacles that needed B Ability™ System 800xA simulator to do a virtual start-



Aasta Hansteen tow from Stord to the field, photo: Woldcam/Equinor

<http://www.abb.com/cawp/seitp202/4160929811931378c12582f2003c782b.aspx>



# Examples of automatic startup of plant

YOKOGAWA

Operators do not require any specialized engineering training to configure sequences.

## The Challenges for Nippon Shokubai

In 2001 Nippon Shokubai built a new NVP (N-vinylpyrrolidone - a raw material used in pastes and photoresist coating) plant that used state-of-the-art technology. The prestigious Chemical Engineering Magazine subsequently conferred its Kirkpatrick Honor Award upon the company in recognition of this plant's safe and clean production of NVP using an innovative vapor phase continuous reaction processes and a new dehydration catalyst.

Nippon Shokubai faced a challenge in constructing an automatic start-up and shutdown system for production processes using this plant's DCS (Distributed Control System) as the new technology used in the plant produced frequent changes in operating conditions. As the DCS was not the best platform for controlling the plant through sequence programs, the company installed Exapilot so that start-up and shutdown sequences could be automated quickly, in spite of the demanding operating conditions.

## Results

Exapilot succeeded in reducing operators' workloads dramatically at the time of plant start-up and shutdown. Before Exapilot was introduced, an operator had to constantly make manual adjustments to the DCS. Exapilot achieved a fully automatic system as follows:

1. A drastic reduction of DCS manipulations: from 4,350 times per month to 0 (zero)
2. DCS monitoring time reduction from 138 man-hours per month to 1 man-hour per month
3. Lower power consumption and heat steam energy as the result of stabilized operations and minimized operation time
4. Elimination of problems caused by operator errors

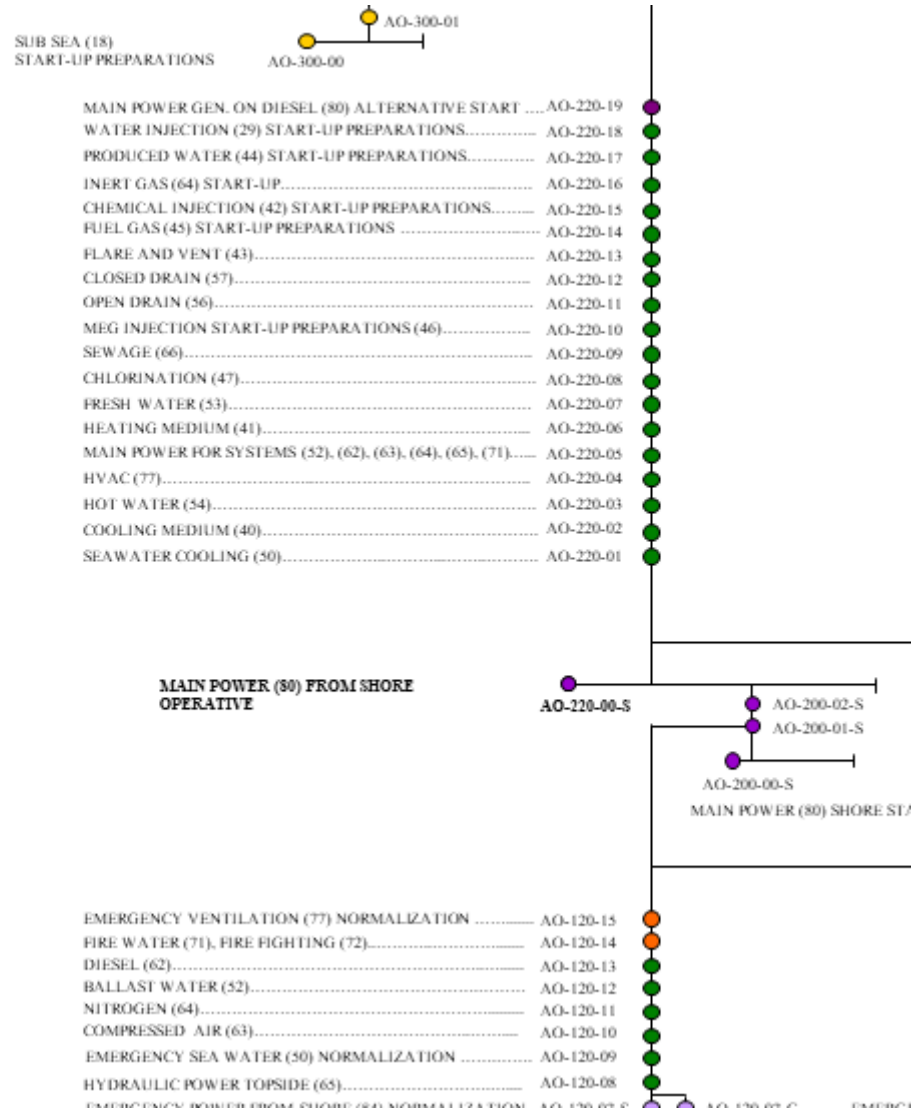
<https://www.yokogawa.com/library/resources/references/drastic-reduction-in-operator-workloads-and-faster-plant-startup-and-shutdown-nippon-shokubai-co-ltd/>

# Automatic startup of plant

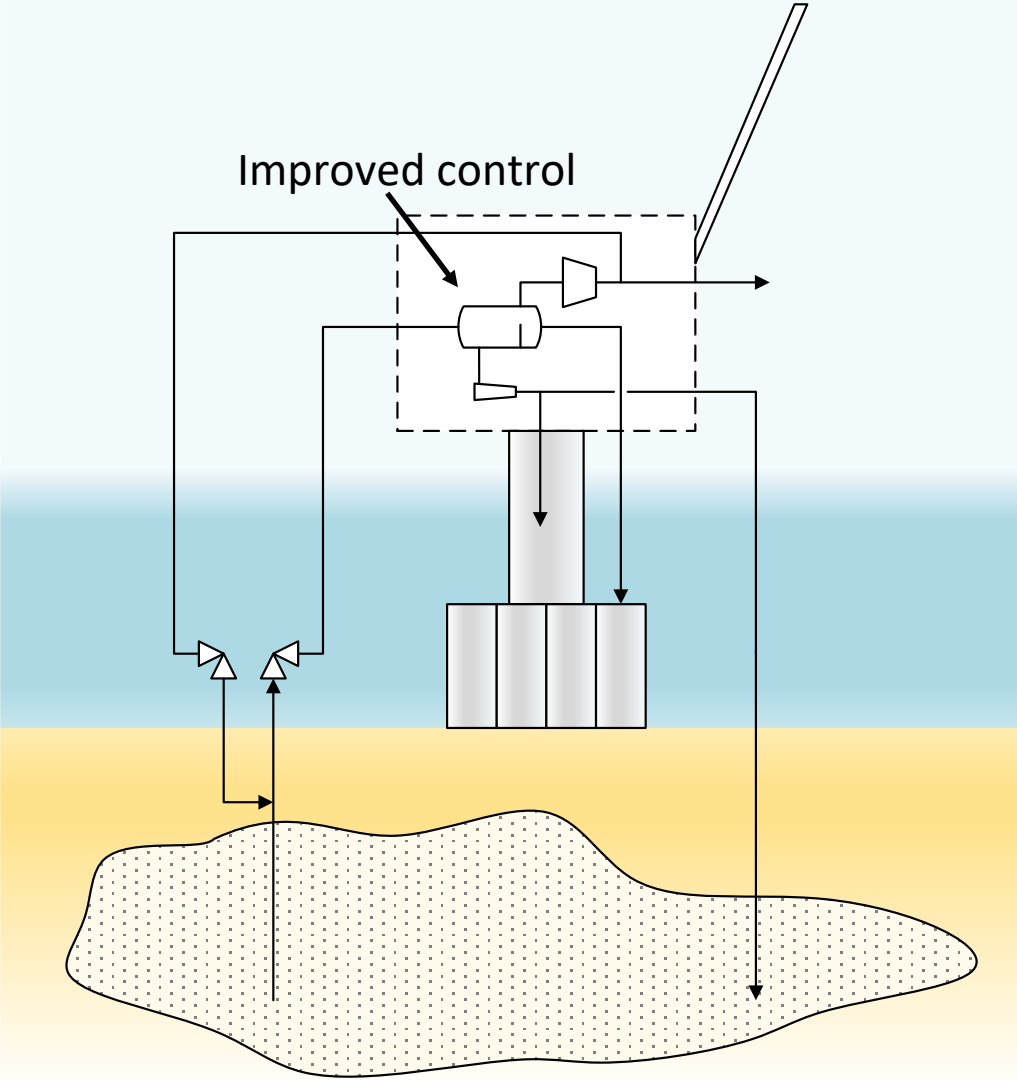
Procedure for startup/shutdown usually already exists.

Today's practice: Use experts knowledge and turning the procedures sequences.

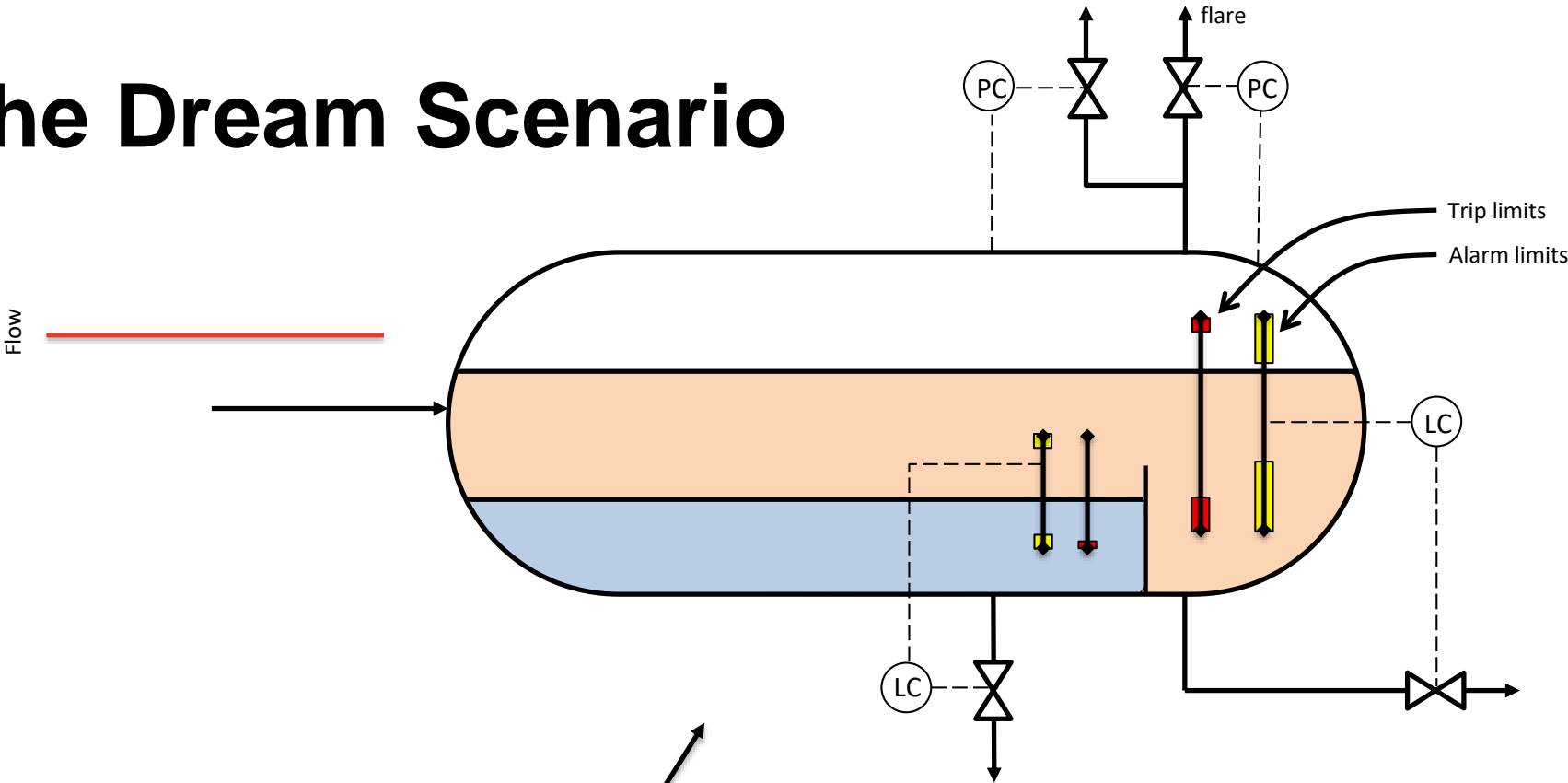
- Testing on simulator
- Tuning, tuning and tuning after commissioning



# Improved Control

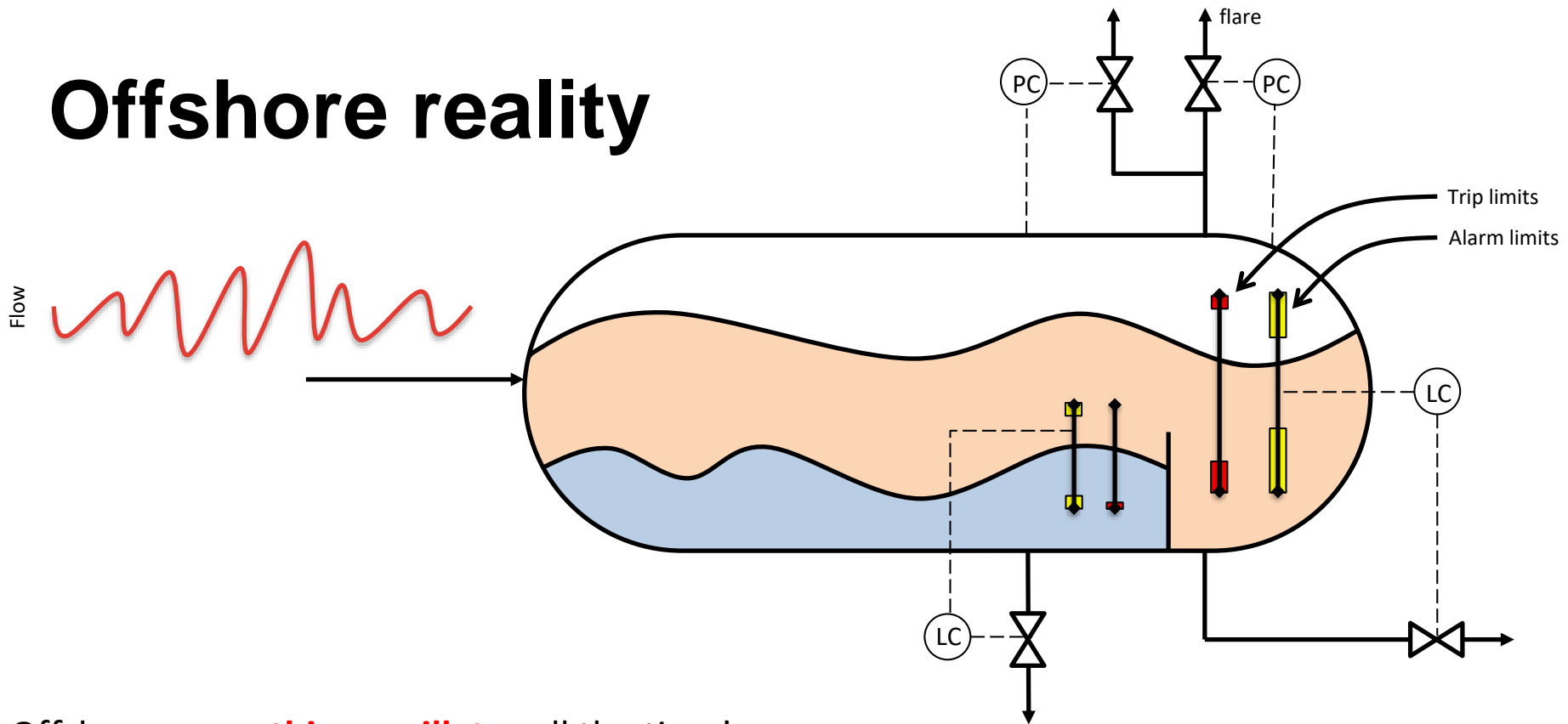


# The Dream Scenario



A first stage separator on an oil platform

# Offshore reality



Offshore: **everything oscillates** all the time!

**Controllers are tuned slow** to dampen flow variations as much as possible for downstream units

Problem: you usually **need faster controllers during startup**

# Improved Control

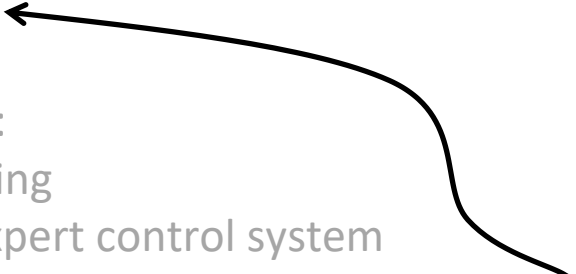
Improving controller performance for a wider range of situation

Manual tuning

Adaptive tuning:

- Gain scheduling
- Heuristics, expert control system
- Fuzzy gain scheduling
- Self-tuning (direct, indirect)
- Auto-tuning

Most issues can be solved with proper tuning



Improved control structure:

- Override controllers
- Correct ratio control

Advanced Controllers:




- MPC
- Higher order linear, Nonlinear
- Neural Net

# Improved Control

Improving controller performance for a wider range of situation

Manual tuning

Adaptive tuning:

- Gain scheduling  e.g. High level -> 2x gain
- Heuristics, expert control system  e.g. Startup -> 2x gain
- Fuzzy gain scheduling  e.g. fuzzy gain scheduling
- Self-tuning (direct, indirect)
- Auto-tuning

Improved control structure:

- Override controllers
- Correct ratio control

	<i>Small valve opening</i>	<i>Large valve opening</i>
<i>Low level</i>	Normal	2x gain
<i>High level</i>	2x gain	Normal

Advanced Controllers:

- MPC
- Higher order linear, Nonlinear
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# Improved Control

Improving controller performance for a wider range of situation

Manual tuning

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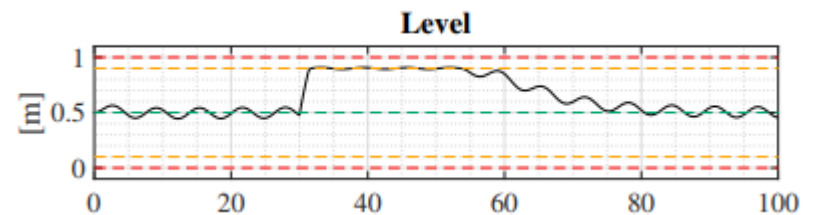
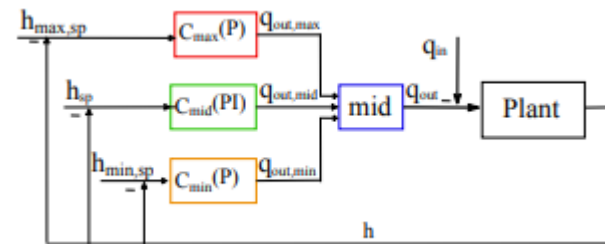
Improved control structure:

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Common industrial solution



Adriana Reyes-Lúa, Christoph Josef Backé, Sigurd Skogestad (2018). Improved PI control for a surge tank satisfying level constraints. IFAC-PapersOnLine 51(4), 835-840

# Improved Control

Improving controller performance for a wider range of situation

Manual tuning

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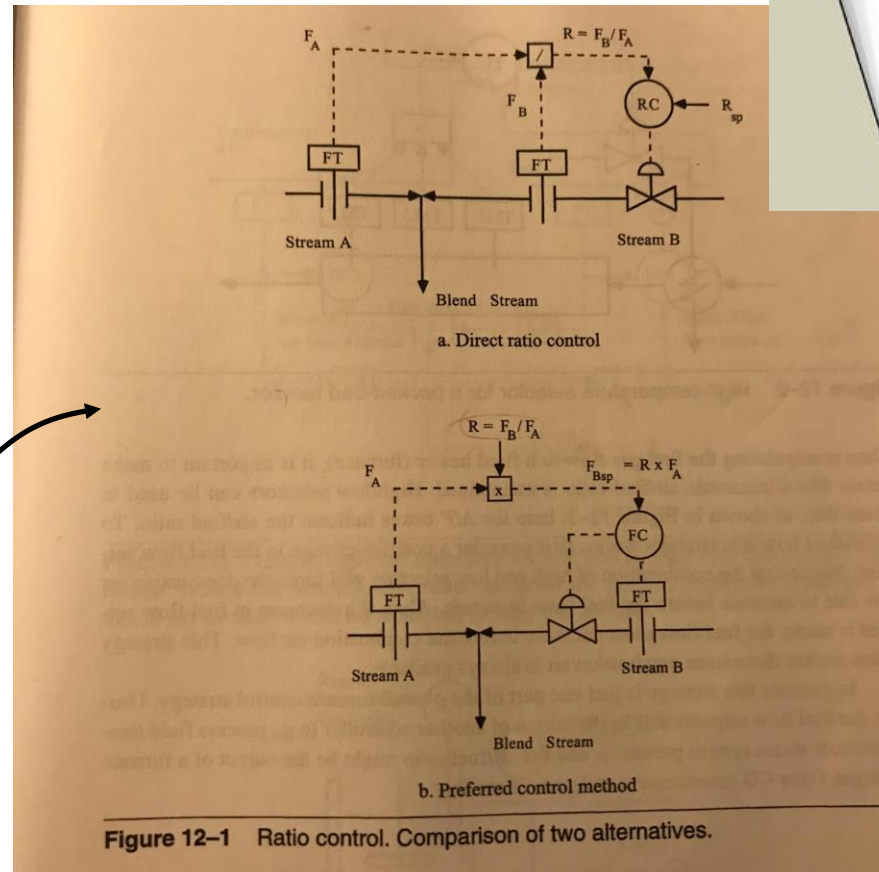
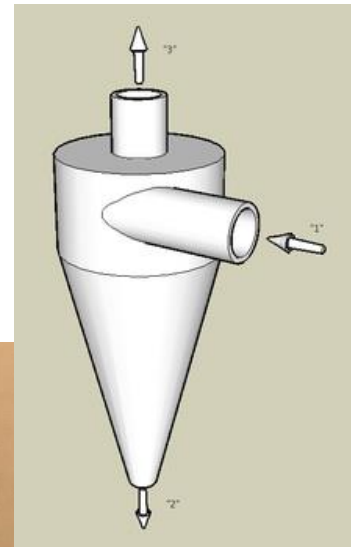


Figure 12-1 Ratio control. Comparison of two alternatives.

Bequette, B. W. (2003). *Process control: modeling, design, and simulation*. Prentice Hall Professional.

# Improved Control

Improving controller performance for a wider range of situation

Manual tuning

Adaptive controllers:

- Gain scheduling
- Heuristics, Expert control system
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- Self-tuning (direct, indirect)
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Improved control structure:

- Override controllers
- Correct ratio control

Advanced Controllers:

- MPC
- Higher order linear, Nonlinear
- Neural Net

- Decouples
- Handles constraints on measurements
- Handles bottlenecks
- Possible with prioritization on soft-constraints

**Probably no MPC offshore applications in Norway**

# What Does the Modern Operator Do?

## Field operations

- Operating manual valves
- Prepare for maintenance
- Sample taking/analyze quality
- Validating measurements
- Inspections rounds:  
visual, smells, vibration, sounds, temperature

## Startup operations

- Startup and shutdown of plant
- Procedural operations like changing pumps, pigging, etc.

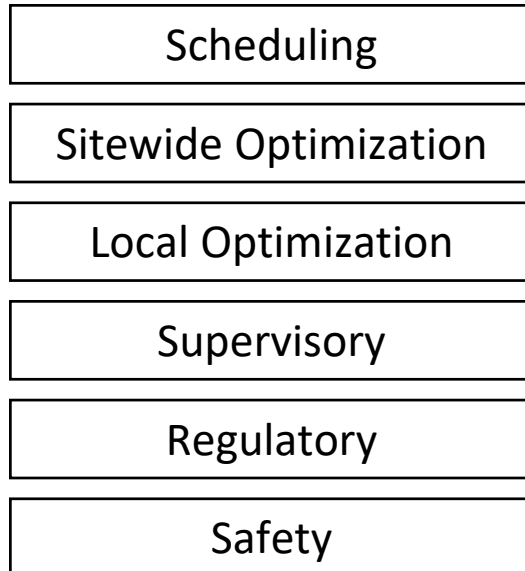
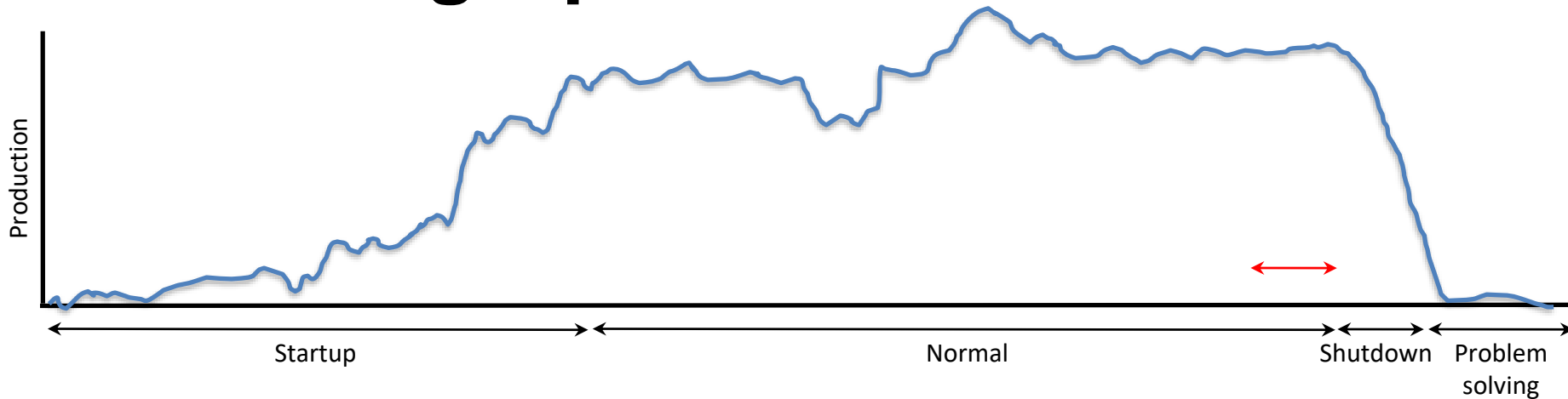
## Monitoring operations

- Fault detection and correction
- Validating measurements
- Intervene when the plant is approaching some safety limit

## Production operations

- Handling bottlenecks
- Backing off from constraints
- Controlling quality



# Monitoring Operations

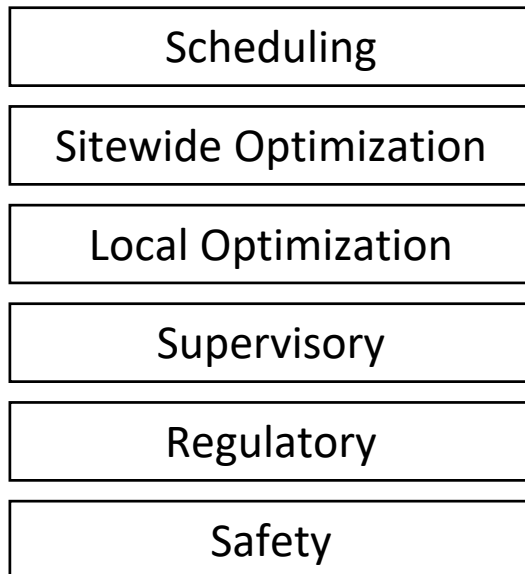


Operator


How can we push the operator up?

# Fault Detection, Diagnosis and Mitigation

Can be worked around  Irrecoverable   
Fault vs. Failure

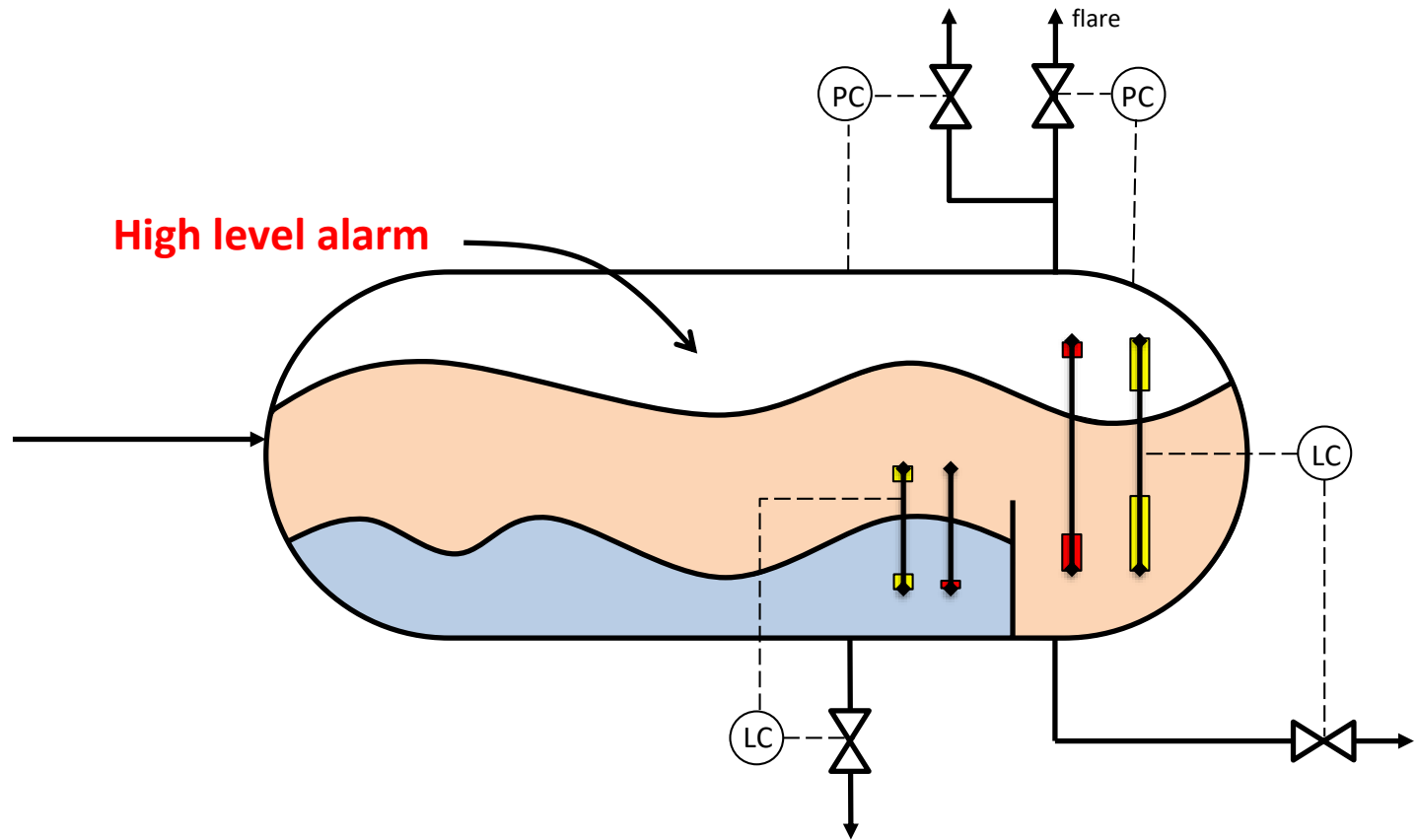


Alarms: The simplest fault detection method

 Detects failure and shuts down the plant  
e.g. reactor temp > 200 °C -> Trip plant

Mogens Blanke, Michel Kinnaert, Jan Lunze, Marcel Staroswiecki (2018). Diagnosis and Fault-Tolerant Control. 2<sup>nd</sup> Edition. Springer. ISBN: 978-3-540-35652-3.

# Manual Operation



Why:

- Large disturbance?
- Is the level measurement correct?
- Is the valve working?

Probably not acceptable to shut down the platform because of a faulty sensor



# Automated Solutions for Fault Detection, Diagnosis, and Mitigation

## Detection:

- Analytical
- Data-Driven
- Knowledge Based
- Fuzzy Logic
- Pattern-Recognition

Eg, Alarm limit

Eg. Large deviation between the two oil level measurements

e.g. Principal Component Analysis (PCA)

Bakdi A, Kouadri A. An improved plant-wide fault detection scheme based on PCA and adaptive threshold for reliable process monitoring: Application on the new revised model of Tennessee Eastman process. Journal of Chemometrics. 2018;32:e2978. <https://doi.org/10.1002/cem.2978>

## Diagnosis

e.g. Deep Learning

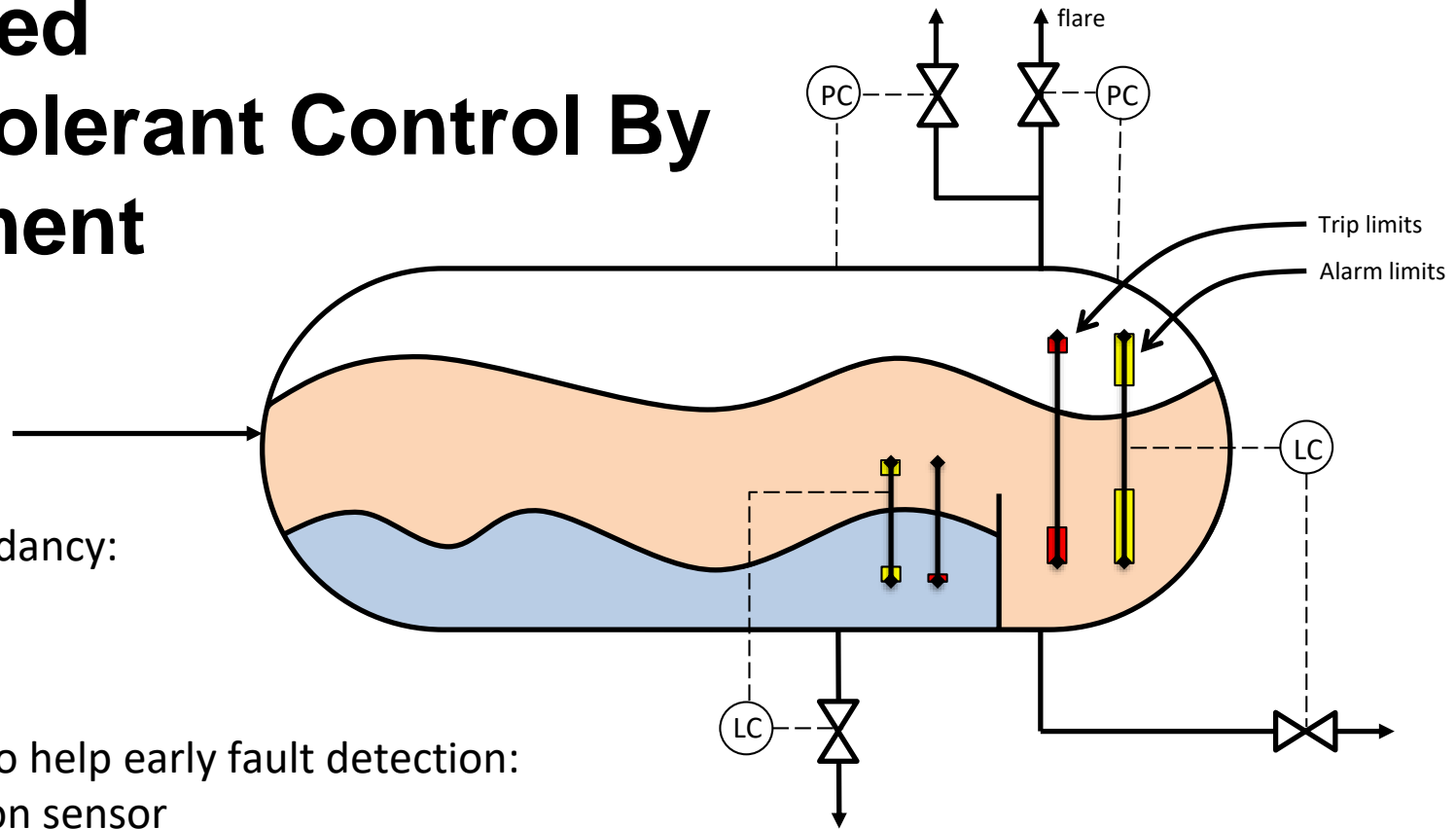
Lv, Feiya & Wen, Chenglin & Bao, Zejing & Liu, Meiqin. (2016). Fault diagnosis based on deep learning. 2016 American Control Conference (ACC). 6851-6856. 10.1109/ACC.2016.7526751.

## Mitigation:

- Virtual/soft sensors
- Virtual actuators

Many solutions, but not widely adopted in industry...  
Must be considered much more in operatorless future

# Improved Fault Tolerant Control By Equipment



## Physical Redundancy:

- Sensors
- Actuators

## Extra sensors, to help early fault detection:

- Valve position sensor

## Robust Equipment:

- Sensors: e.g. rather orifice than ultra-sonic
- Actuators: not sensitive to scaling

Two sensors, detect error but must shut down.

Tree sensors, can detect error and continue controlling

# What Does the Modern Operator Do?

## Field operations

- Operating manual valves
- Prepare for maintenance
- Sample taking/analyze quality
- Validating measurements
- Inspections rounds:  
visual, smells, vibration, sounds, temperature

## Startup operations

- Startup and shutdown of plant
- Procedural operations like changing pumps, pigging, etc.

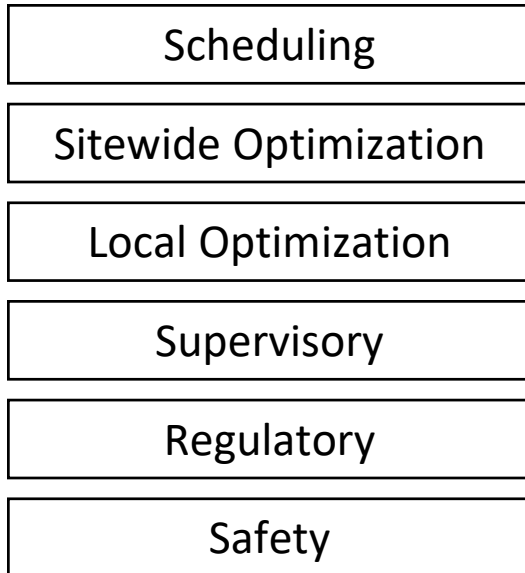
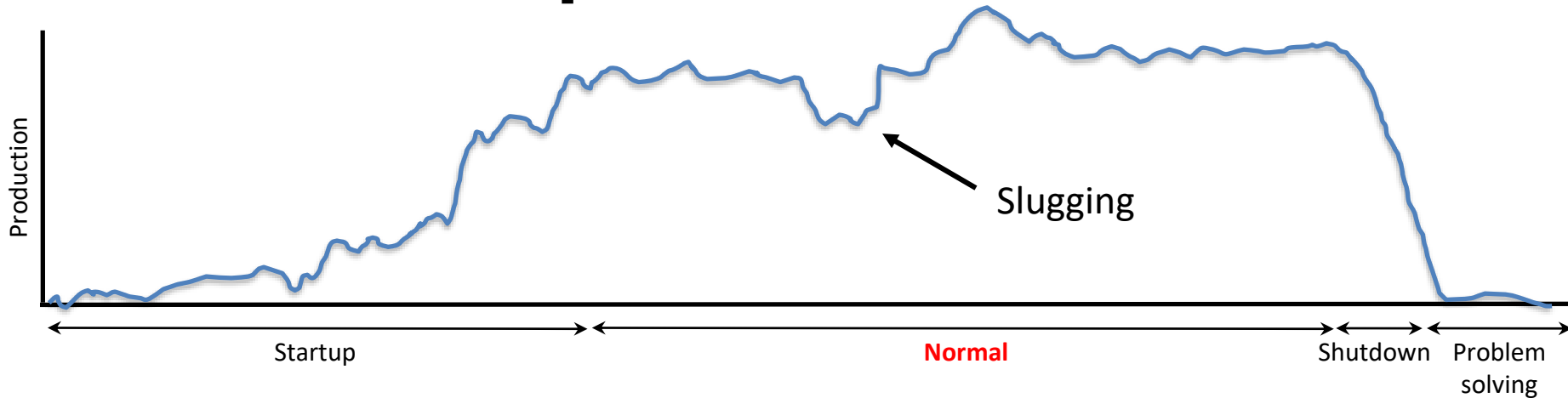
## Monitoring operations

- Fault detection and correction
- Validating measurements
- Intervene when the plant is approaching some safety limit

## Production operations

- Handling bottlenecks
- Backing off from constraints
- Controlling quality

# Production operations

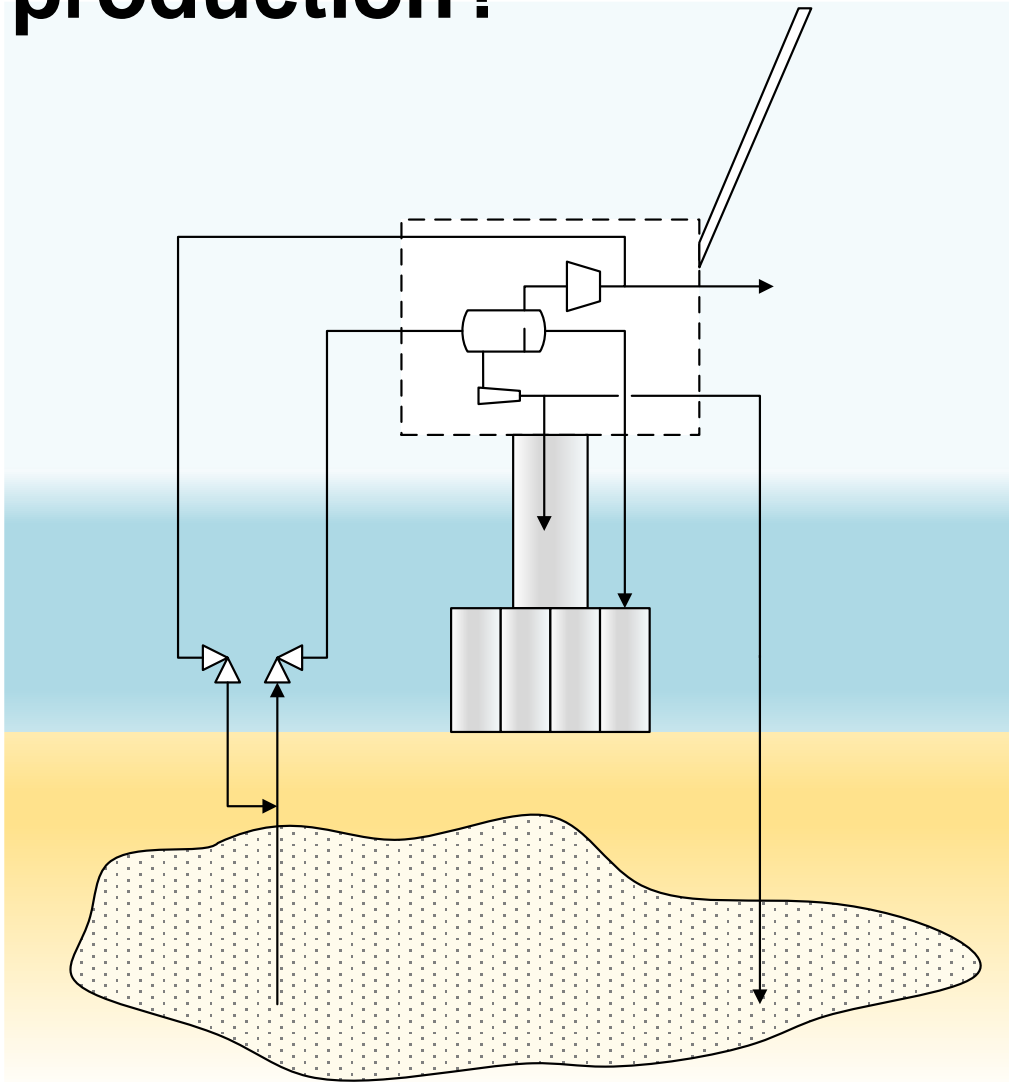


Operator

How can we push the operator up?



# Why does the Operator reduce production?



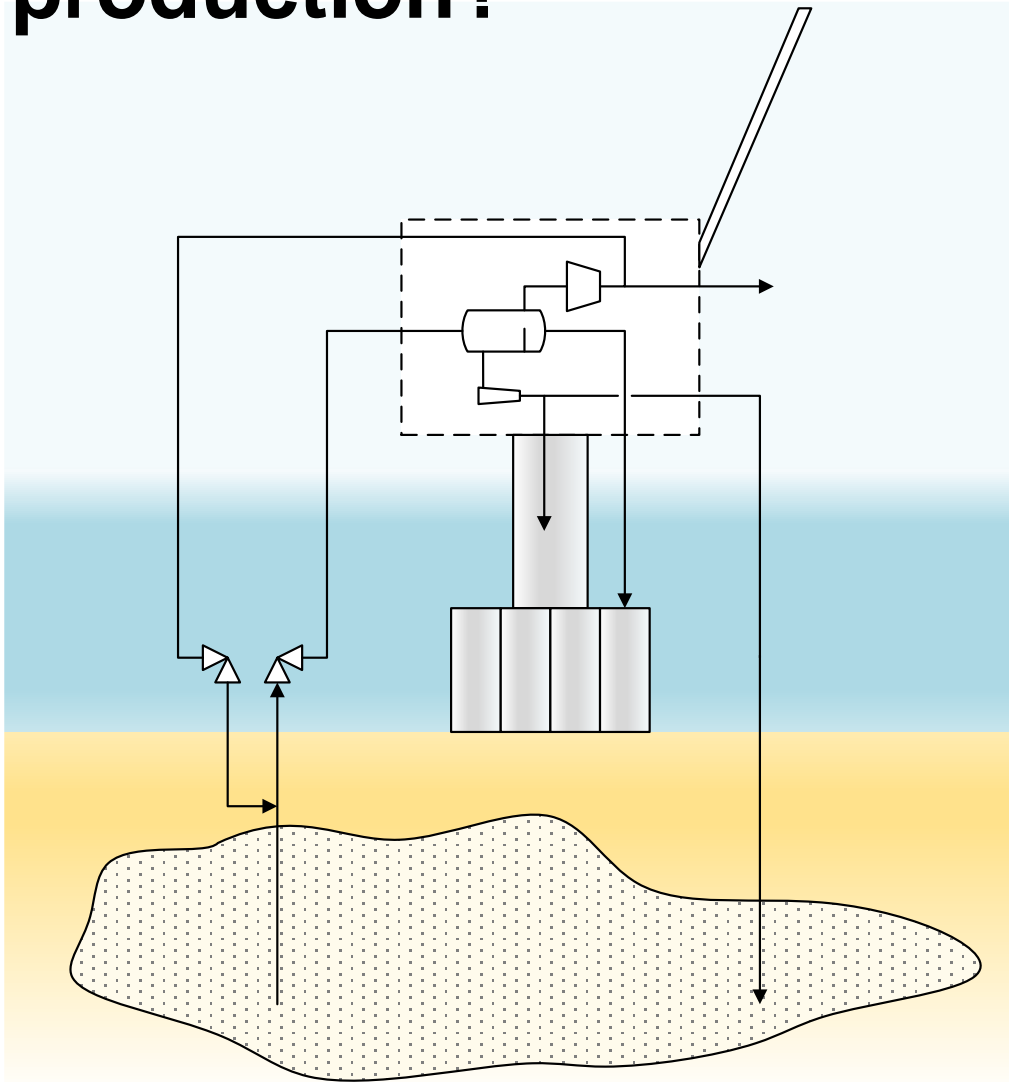
**Production rates are given.**

Each well has:

- Startup priority
- Target bottom hole pressure
- Target gas lift rate

Why does the operator choke back?

# Why does the Operator reduce production?



**Production rates are given.**

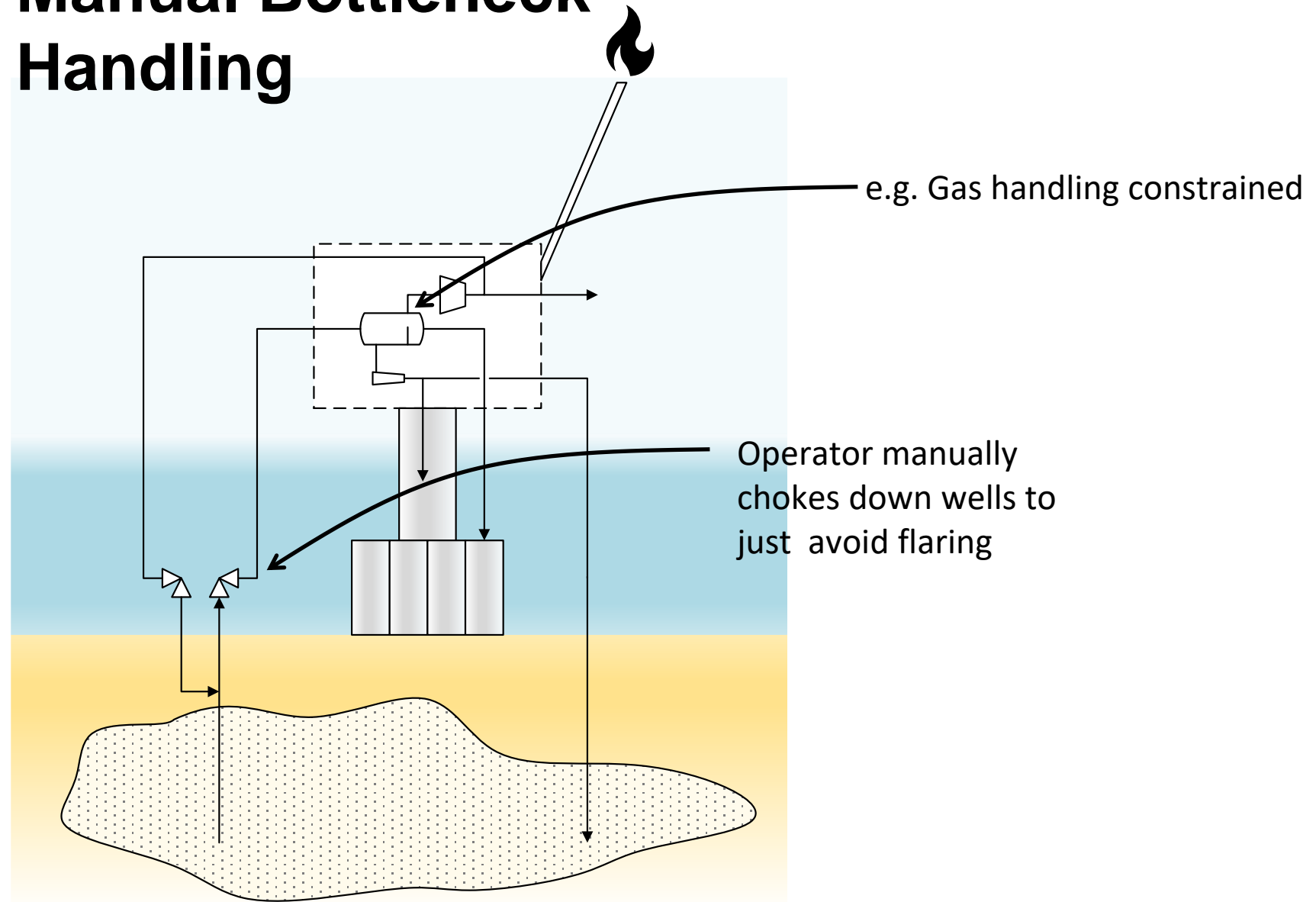
Each well has:

- Startup priority
- Target bottom hole pressure
- Target gas lift rate

Why does the operator choke back?

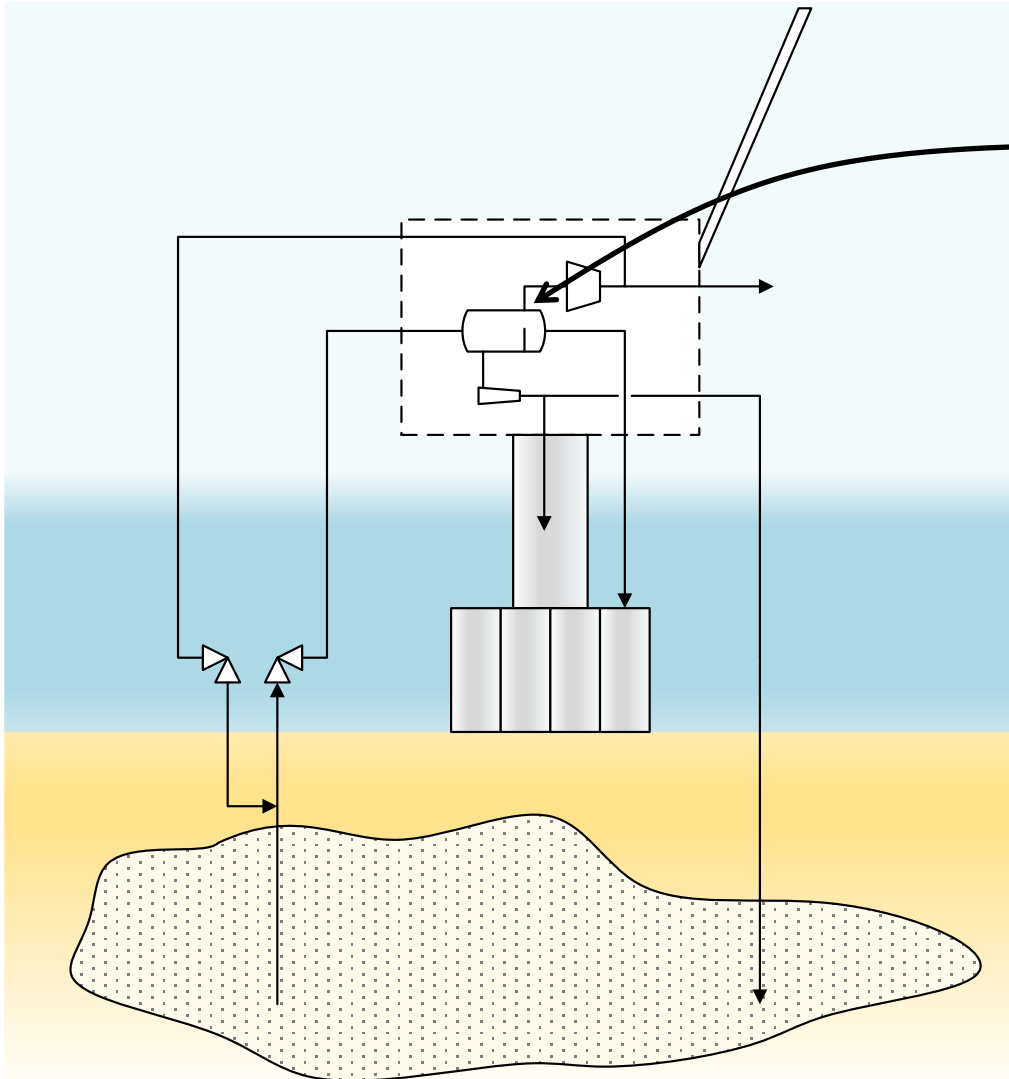
- Bottlenecks
- Back-off from constraints

# Manual Bottleneck Handling



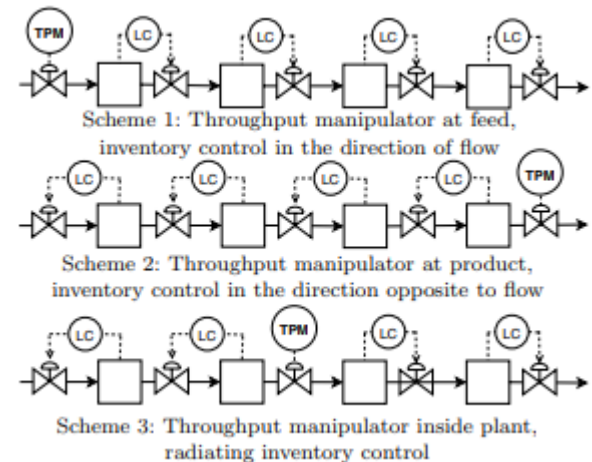


# Automatic Bottleneck Handling



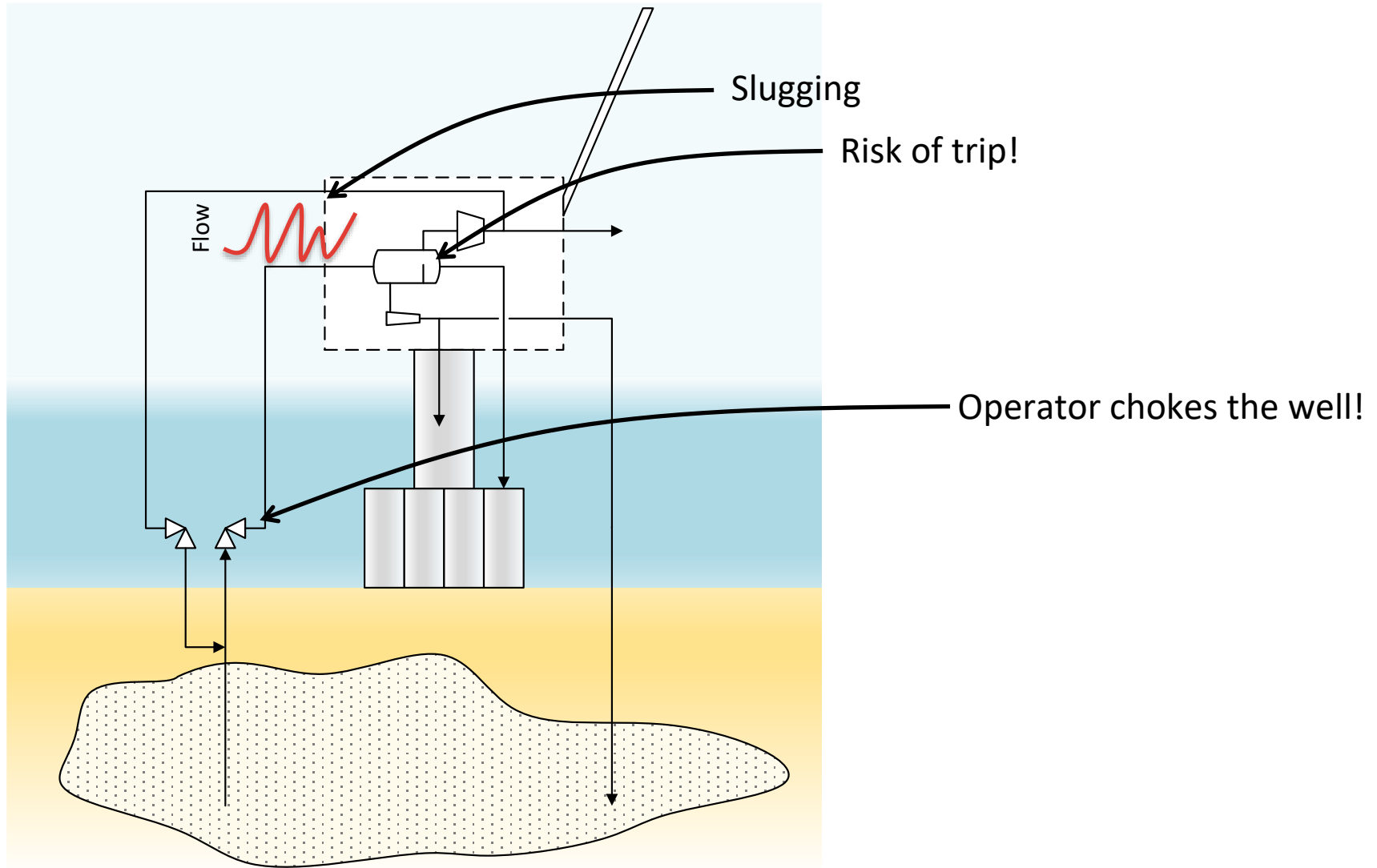
e.g. Gas handling constrained

Need to take into account constraints and how this affects the control structure

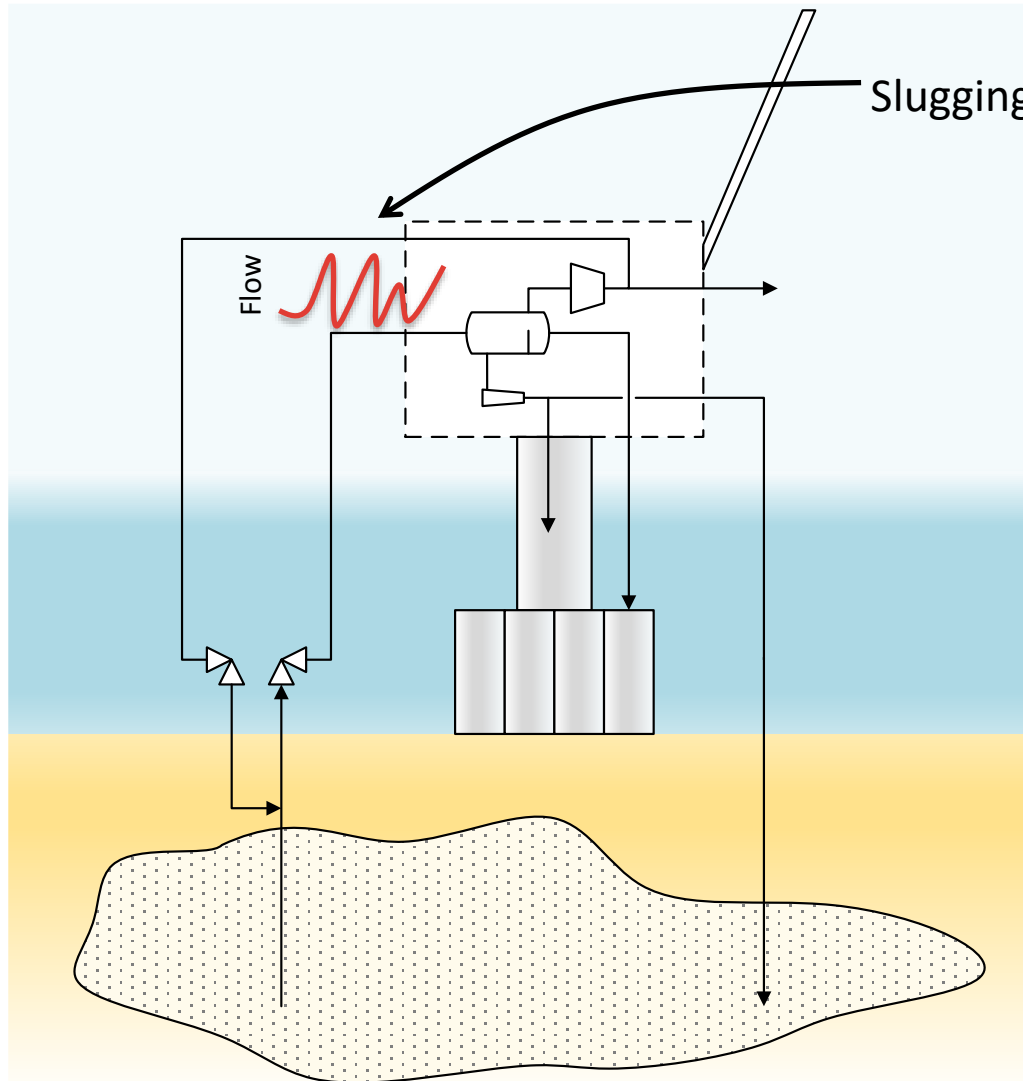


Elvira Marie B. Aske, Sigurd Skogestad, Stig Strand (2007). Throughput maximization by improved bottleneck control. IFAC Proceedings Volumes, 40(5), Pages 63-68

# Back-off because of Slugging



# Current Automatic Solutions to Slugging



Different apaches:

- Overload Avoidance
- Slug Mitigation
- Stabilization (wells, pipelines)

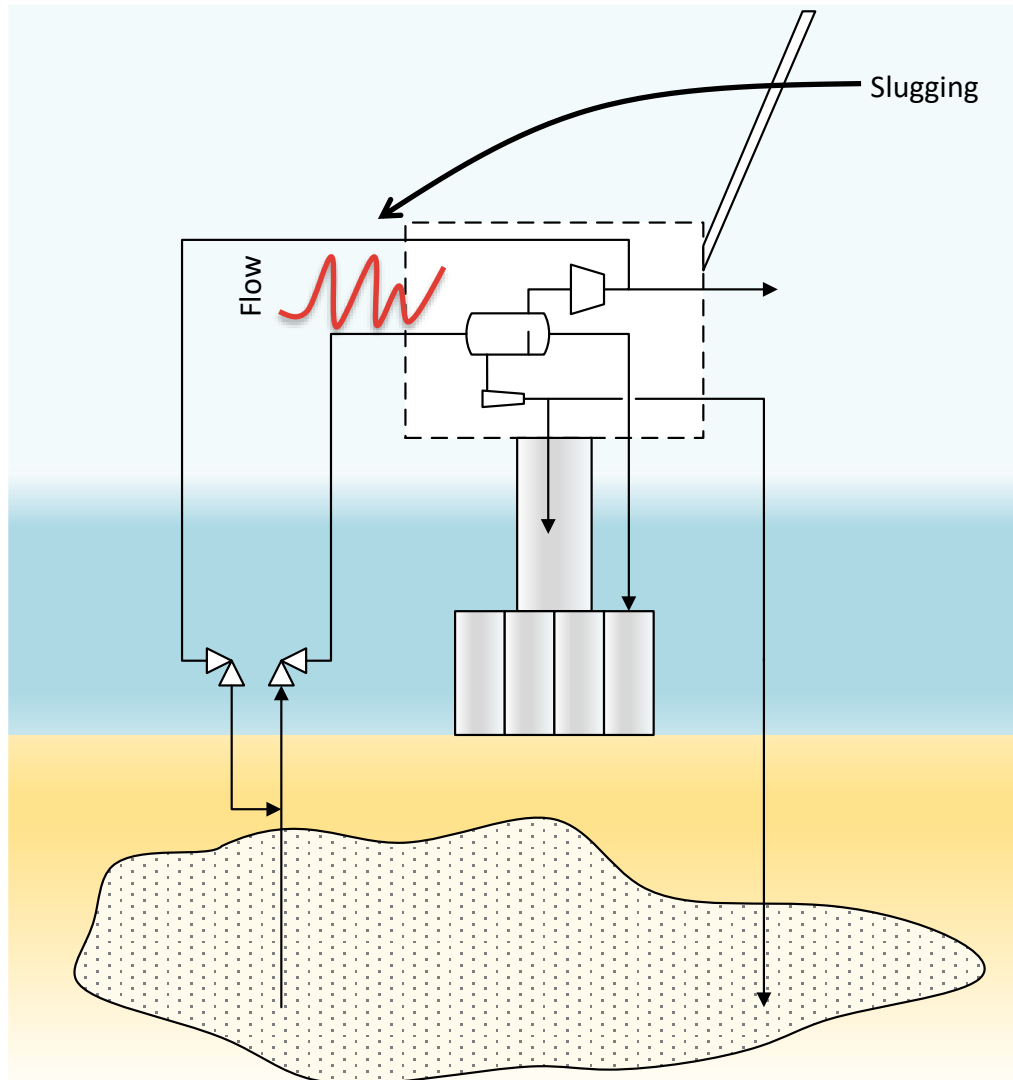
Ideally stabilize the slugs

- Squeeze and shift in process
- Increased production from the wells

Stabilizing is difficult:

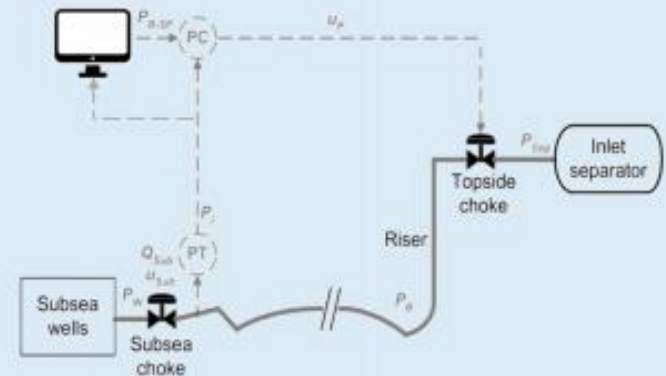
- Changing process dynamics
- Small sett of parameters that stabilize
- Often slow valve

# Next Generation Slug-Controller?



## New NTNU solution

- Setpoint updated *automatically* to avoid slugging and maximize production
- Controller parameters adjusted *automatically*



Vinicius de Oliveira, Johannes Jäschke, Sigurd Skogestad (2015). An autonomous approach for driving systems towards their limit: an intelligent adaptive anti-slug control system for production maximization, IFAC-PapersOnLine, 48(6), Pages 104-111, ISSN 2405-8963

# Final Thoughts

- Operatorless plant, closer than we think?
- The push for unmanned production platforms will make operatorless more likely
  - Because of more focus on measurements, actuators, and redundancies.
  - Because process design will be simplified.
- Gradual transition, reducing the number of operator...
- First iterations does not need to be optimal, just better than what now.

# Additional References

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