Virtual Laboratory based on Node.js technology

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Abstract - The paper demonstrates remote control of test experiment in the virtual laboratory. This is a common problem, but another way can always be used to solve it. The paper compares several existing virtual laboratories and their possible issues at present. To develop such a new solution JavaScript technology was used on both client and server side using Node.js runtime.

Keywords – virtual laboratory; javascript; node.js; rest services; angular framework; mongodb; matlab;

I. INTRODUCTION

Practical exercises in the laboratory are important part of the process of training people with technical background in general. Ancient Chinese philosopher Confucius once said: "Tell me, and I will forget. Show me, and I may remember. Involve me, and I will understand" [1]. We know from experience that man can learn in the fastest way when he tries things several times, and after that he understands how it works. Unfortunately, you cannot always provide direct access to real devices to perform the experiment for researchers or students. There may be several issues: the higher price of laboratory equipment, workplace safety (depending on the experiment), or lack of qualified assistants.

In recent years, the development of virtual machines has increased mainly due to the technological evolution of software engineering. The progress of modern technology gives us the better approach to solve new challenges, while creating whether the virtual systems for online teaching, or specific virtual laboratories where physical processes can be simulated. In experiments conducted in a virtual environment, it is possible to share resources of this environment for more connected users who want to perform the same experiment, which would not be possible in our computers. This makes virtual laboratory a good complement to study whether research, where you can try different variations of the experiment without risk to health or destruction of the device. Later, experiments can be tested on real devices, if necessary.

II. VIRTUAL LABORATORIES

At the time when the Internet was not yet widespread in use, the experiments were done in real laboratories. It was important to keep on with different safety regulations to the possibility of personal injury or damage to equipment.

Distance and lack of financial resources makes real experiments difficult to perform, especially in cases where it is

necessary to have some advanced and sophisticated tools. Another encountered problem is the lack of good teachers. Although at present time there are already online courses that provide instructional videos, but it solves the problem only partially. Thanks to internet experiments can be structured for visualization and control remotely. Nowadays, a lot of equipment already provides an interface to connect computer and process data from it. Experimenting over the internet allows the use of resources, knowledge, software and data when physical experiments cannot [2].

In this paper, we discuss the creation of virtual laboratory (VL). Before we describe the list of technologies to create VL, we must explain what we consider under VL. Generally, we can say that VL is a computer program, where students interact with the experiment by the computer via the Internet as it is depicted in the Fig. 1.

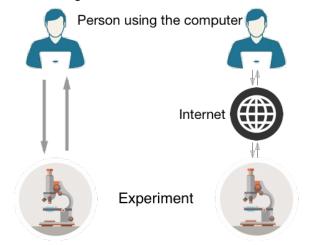


Fig. 1. The difference between a face-to-face and remotely controlled experiments.

A typical example is the simulation experiment, where the student interacts with the web/app interface. Another possibility is a remote-controlled experiment where the student interacts with the real device via the computer interface, although he can be far away. This is the case when a virtual laboratory turns into a remote laboratory.

When web exclude the second option, so we have the following definition: "We call it a virtual laboratory where the student interacts with the experiment, which is physically at distant from him or her and not to demand any physical reality".

After explaining what is VL look at the benefits they can bring. They are described in the Tab. I below.

 TABLE I.
 COMPARISON OF REAL, VIRTUAL AND REMOTE LABORATORIES. [5]

Laboratory Type	Advantages	Disadvantages		
Real	Real data Interaction with real experiment Collaborative work Interaction with supervisor	Time and place restrictions Requires scheduling Expensive Supervision required		
Virtual	Good for concept explanation No time and place restrictions Interactive medium Low cost	Idealized data Lack of collaboration No interaction with real equipment		
Remote	Interaction with real equipment Calibration Realistic data No time and place restrictions Medium cost	Only "virtual presence" in the lab		

People often think that the main benefit of a virtual laboratory is to replace the real one. But it is not. You cannot replace the experience of the real work with the VL. Although VL is better than no experience. VL should not be seen as providing the maximum possible interaction experience.

A. Existing solutions

There are currently many different virtual and remote laboratories, which are used by foreign universities for teaching or research. This paper briefly reviews often used laboratories that are accessible over the Internet. A comparison of functionality and the use of technology can be seen in the Tab. II, where different virtual laboratories created in the world are summarized.

 TABLE II.
 COMPARISON OF VIRTUAL LABORATORIES CREATED OUTSIDE OF FEI STU [3].

Name of VL	Client technology	Server technology	Simulation software
Weblab-	AJAX, Flash, Java	Web services,	Xilinx-
DEUSTO	applets, LabVIEW,	Python, LabVIEW,	VHDL,
	Remote panel	Java, .NET, C, C++	LabVIEW
NCSLab	AJAX, Flash	PHP	Matlab,
			Simulink
ACT	HTML, Java applets	PHP	Matlab,
			Simulink
LabShare Sahara	AJAX, Java applets	Web services, Java	Java
iLab	HTML, Active X, Java applets	Webservices, .NET	LabVIEW
RECOLAB	HTML	РНР	Matlab, Simulink
SLD	AJAX, HTML	Webservices, PHP	Matlab, Simulink

There are also some from our Faculty of Electrical Engineering and Information technology in the Tab. III.

 TABLE III.
 COMPARISON OF VIRTUAL LABORATORIES CREATED AT FEI

 STU [4].

Year	Author	Simulation	Data	Client	Server
		software	flow	technology	
2011	R. Farkaš	Matlab, Simulink, Real device	JMI Sockets	Java	Java
2012	T. Borka	Matlab, Simulink, Real device	WCF	.NET WPF	.NET
2014	M. Kundrát	Matlab, Simulink	JMI SOAP	HTML JS	Tomcat Java JSF EJB3 MySQ L
2014	T. Červený	Matlab, Simulink	JMI HTTP	HTML JS	Jetty, Java
2015	Š. Varga	Matlab, Simulink	COM HTTP	HTML JS	.NET, PHP

B. Disadvantaged of existing solutions

At the beginning of the design of a virtual laboratory it was appropriate to examine the possibilities of existing solutions. It is important to avoid various design issues. Alternatively, technologies that have been used are already outdated. Nowadays, the development of new technologies is incredibly fast. Such an analysis of existing solutions we have done in the previous section. Our aim was to create a cross-platform solution using one programming language on client and server side, which cannot be done with WCF or COM technology as in the previous solutions. JMI is only suitable for solutions where Java platform is used. The server cannot be used also with LabVIEW technology or .NET (multi-platform version -.NET core is already under development). Client solutions such as Flash, ActiveX and Java applets are no longer supported in browsers, so their use is not appropriate.

C. Components of virtual laboratory

There are plenty of existing laboratories, but usually it is not possible to guarantee compatibility between them, because there is not a solid standard. Anyway, it is always possible to identify the basic components that virtual laboratories can use. Some of them can be even used more times.

Components:

- The experiment itself.
- The device with possibility to control and acquiring data.
- Laboratory server, which provides control, monitoring and data processing of the experiment.
- Server providing connection between remote users and laboratory server, usually via the internet.
- Web camera connected to a server, which can be used for remote user as a visual and audible feedback on the actual status of the experiment.
- Tools enabling multi-user audio, video and chat communication.

Client software controlling and representing data of the experiment [6].

It is important to realize which of these components could be used, because for creation of a virtual laboratory it isn't necessary to have them all. Alternatively, others that are perfectly suited for a role can be used also. Sometimes it is used e.g. database server if experiments will be stored and processed later. It is also important to realize what type of VL we want to create. Certainly, differences will be in the design of single-user as opposed to multi-user VL, even with multiple experiments simultaneously. It should bear in mind as properly solve the scalability, potential safety issues, multi-user access and other possible issues.

III. ARCHITECTURE PROPOSAL

As the main component Node.js was selected. It is the server which handles communication between components of VL. The parts of architecture will be explained based on Fig. 2. The data are fetched periodically from Simulink into Matlab workspace. In the beginning, it was not sure whether it would be possible to achieve to run multiplatform soft real-time Simulink based simulations. Because only Windows based solution was found directly from MathWorks. For our solution *Real-Time Pacer* [7] was used that allows us to run simulations in soft real-time even under macOS or Linux. It is used to slow down the simulation to the soft real-time.

To communicate with RESTful web service Matlab R2015a uses the built-in rarely used function *webread* and *webwrite* [8]. Firstly, simulation must be run through web browser, after that data will be transferred over *socket.io* library channel. These data will be shown in the graph of web browser and it is possible to save them to MongoDB database for later processing (Fig. 2).

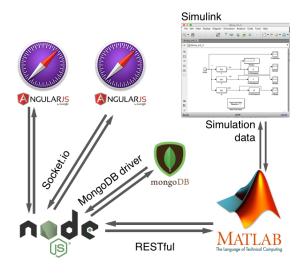


Fig. 2. Design of communication between components.

A. Reference simulation model

For a development purpose we used the simulation of dynamic system called projectile motion implemented in Simulink that runs through the web interface. This simulation needs to be run with two files. Purpose of the first is the initialization of variables needed to calculate the coordinates of the point. This experiment has three parameters. The first and second parameter are initial values for simulation. The last parameter userFromWeb is not necessary for simulation itself, but it is important to identify user who runs the simulation. This makes it possible to assign the simulation results in later processing from the database.

B. Experiment handler

The second Matlab file is a handler code sending the data to Node.js. Because of its length of implementation, it is not possible to display whole source code, so we describe only the key part.

During initialization the URL path is set for Express.js REST API where Matlab will send the data.

The model is preloaded using the Matlab function *load_system('projectile_motion')*. This function searches in the current folder for *projectile_motion.mdl* file and sets it as the top-level model. After this initial settings, simulation must be run using the command *set_param(model, 'SimulationCommand', 'Start')*.

In the next block of the Matlab code it is running an infinite *while* loop that makes possible to collect data from the simulation to the state until it is complete. Inside of the *while* loop the function *set_param(model, 'SimulationCommand', 'WriteDataLogs')* is called, which is looking for the current top-level simulation. In the soft realtime the calculated data are written to the Matlab workspace. Without that function data would be written only after the simulation ends.

Meanwhile, it is necessary to prepare required format of data for the web service. Thus, before sending them to the REST API it is suitable to wrap data to the JSON structure. We used the Matlab library *JSONlab* v1.2 [9].

A sequence of these two commands is required to create the desired JSON format and send it to Express.js API. Create JSON with the commonad *json* = *savejson('result', struct('user', userFromWeb, 'status', 'Running', 'data', struct('time', timeFinal, 'you', vyFinal, 'y', yFinal, 'x' xfine)))* and transfer it to the service with *response* = *webwrite (URL, JSON, options)*.

The command get_param(model, 'SimulationStatus') is used to check current status of the simulation. If the simulation is still running the status is "running". As soon as the status is "stopped", the loop needs to be stopped using the break keyword and we know that all data is transferred to Node.js.

C. Communication between components

One of the aspects among the individual components of the laboratory is communication. Although in each component communication works differently, it is still based on the HTTP protocol. The sequence diagram on the Fig. 3 shows that communication starts from the web browser. The user inserts the parameters of simulation, which are sent to StarkLab via the REST web service. This service starts Matlab on the current operating system with the necessary files and simulation parameters. Meanwhile, the user waits until Matlab starts in the background. Simulation is immediately initialized and starts sending data to StarkLab, which sends them directly to the web client from where the simulation has been originated. All the received data will be reflected to the chart, animation and table in the web browser. This sequence is repeated until the condition contains *SimulationStatus* == "running". After stopping the simulation, the client sends a request to save data through StarkLab directly into the document database MongoDB.

called immediately after form was sent with initial parameters of the experiment from the web browser.



Fig. 4. Start Matlab in command line using shell.js library.

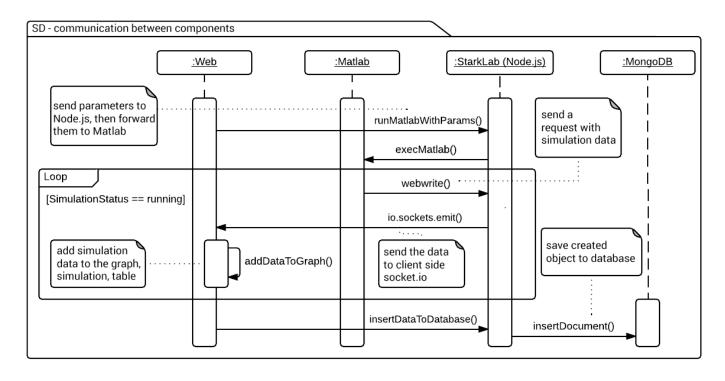


Fig. 3. Communication between components.

D. Run Matlab from command line

At the beginning, it was not clear how to run the simulation. It was necessary to determine whether Node.js allows to carry out the commands of the operating system, respectively run programs. The simulation was working in such a way that the Matlab was opened manually and we put there all the necessary initialization files, then the simulation itself. But this solution is not sufficient in terms of automation and autonomy.

It has been found that Node.js can launch any software that can run through the terminal. To simplify this workflow the *shell.js* [10] library was used which provides such an option.

The sample of code on Fig. 4 shows how Matlab is started via Node.js route http://localhost/matlab/run. This route is

IV. REMOTE CONTROL OF EXPERIMENT

A. Web client created with Angular framework

Client application was created with the JavaScript framework *Angular* [11] (version 1.5.5). The role of the web client was to verify the functionality of the server that sends simulated data. The functionality has been verified, and screens will be described specifically.

Fig. 5 shows login page for web client application. It is authenticated against LDAP server of Slovak University of Technology.

Cogin ×	Erich
\leftarrow \Rightarrow C \Uparrow localhost:30 \circlearrowright O \heartsuit	≝≣
Stark Laboratory	
User xstark	
Paseword	
Sign in Sign	

Fig. 5. Login to web application.

The details of the login process via LDAP is not interesting for this part of the paper. After successful login, the dedicated page for the tested experiment is showed. Our experiment was projectile motion. It takes two parameters to run simulation. On Fig. 6 it can be seen the form that takes two parameters to run simulation. The page is redirected to *http://localhost/matlab* route, where user is waiting to see the data from Node.js REST API.

It redirects to the dashboard page and user has to wait until the start of Matlab simulation. When it starts, user will see new data coming to graph, animation and table in his web browser. This part could be accelerated by powerful server running with the Matlab.

🖰 _{xstark} 🔁	Projectile motion		
➡, Simulations ✓ Real-time data stream	Theory	Parameters	
View simulations	The projectile motion is call a movement of a mass body in the gravitational field where an initial velocity makes with the x-axis nonzero angle. When the angle is positive, i.e. then it is classified as	Velocity v0	-1
	The projection motion upwared. If the projection motion is performed in the six then the mass body is moving along the curved path called the ballistic curve.	Angle Alfa	-1
	Mathematical model	Run	
	Expose that the mass loop has an initial weakly that makes an angle will be hotocated detection. Consequential momentum and a set in high and a first detection of the work of in the original detection by this detection the axis is label and a first detection. The set of the test of the momental is the discussion of the quarking and exposition that can be defined with the y and. There is no methods in the direction of the z-axis (the trajectory will be in the form of a three dimensional convel).		

Fig. 6. Parameters of simulation - initial velocity and angle in degrees.

Visualization of the received data is done by Chart.js library on Fig. 7. Our implementation of chart was created using Angular directive with name *<ui-graph></ui-graph>*. Because of this approach to use Angular components, it can be used multiple times with the same codebase.

At the beginning, it is necessary to get an element from DOM (Document Object Model) tree. Next step is to obtain canvas context and create object with initial data.

The plotted data at the bottom of the picture is identical with the data in the graph. The difference is in the way of implementation as animation. This animation was created using HTML Canvas technology.

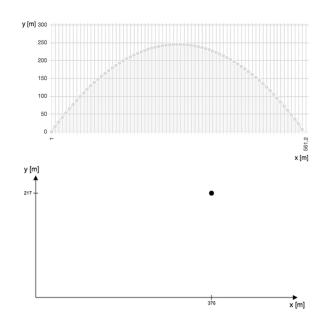


Fig. 7. Graph and Animation of projectile motion in [x, y] position.

The last section, where the data can be seen is a table where data were added over time as well as chart and animation before. In this table Angular databinding [11] is used to set received object as one row with their properties. As simulation runs, the Angular adds new rows to table dynamically.

Simula	tion data	l	8
Time [s]	Axis x [m]	Axis y [m]	Velocity [m/s]
0	0	0	38.57
0.01	0.46	0.39	38.47
0.02	0.92	0.77	38.37
0.03	1.38	1.15	38.27
0.04	1.84	1.53	38.17
0.05	2.3	1.92	38.08
0.06	2.76	2.3	37.98
0.07	3.22	2.68	37.88
0.08	3.68	3.05	37.78
0.09	4.14	3.43	37.68
0.1	4.6	3.81	37.59
0.11	5.06	4.18	37.49
0.12	5.52	4.56	37.39
0.13	5.98	4.93	37.29
0.14	6.43	5.3	37.19
0.15	6.89	5.67	37.1
0.16	7.35	6.05	37

Fig. 8. Table data - time, x, y, vy values of projectile motion experiment.

This system is not only about the real-time rendering of data, but also for later viewing and processing of them. On the site of simulations, we can see all the entries for the currently logged in user – Fig. 9. The list is obtained from MongoDB using Angular *\$http.get(url, callback)* function from web client to our Node.js server, which can have access to database.

When the one of the results is opened, the output looks the same as in Fig. 7, but it is possible to set data sampling and time of simulation. The second option is about time rendering. There are two options: to see data output immediately or soft real-time as it was firstly run.

List of simulations

User	Date	Model	View	Delete
xstark	09.04.2016 11:39	projectile	•	Î
xstark	09.04.2016 11:42	projectile	•	Î
xstark	13.04.2016 09:22	projectile	•	Î
xstark	13.04.2016 09:23	projectile	•	Î
xstark	13.04.2016 09:23	projectile	•	Î
xstark	14.04.2016 02:00	projectile	•	Î
xstark	14.04.2016 02:00	projectile	•	Î
xstark	14.04.2016 02:00	projectile	•	Î
xstark	14.04.2016 11:41	projectile	•	Ĩ
xstark	14.04.2016 11:46	projectile	•	Ĩ
xstark	14.04.2016 11:52	projectile	0	Î
xstark	14.04.2016 11:53	projectile	0	
xstark	14.04.2016 11:54	projectile	0	Î

Fig. 9. Table of saved simulation for currently logged user.

V. CONCLUSION

After the experience with this kind of development, we assess that the creation of virtual laboratory platform on Node.js development was easier thanks to the use of JavaScript on the server and client side. We thought that due to the single thread loop of Node.js would handle more clients and simulations than similar solution on a different platform. The problem was not in many of registered users, but only when we run multiple simulations in Matlab. In our test computer - MacBook Pro there was already a problem with two parallel simulations. It can be improved using powerful server for Matlab calculations.

The work is not over yet and StarkLab can be extended with another interesting functionality such as the creation of unified protocol for data interchange. Suitable would be also interfaces for other calculation and simulation software. Matlab deployment on a separate server with an available domain would help to availability. Another interesting functionality would be uploading simulation and calculation scripts through a web interface.

The current solution is not possible to deploy into production without certain modifications and integrations, but it might serve as a solid basis for adding new features. There are many ways to improve this solution.

All code is open source available at https://github.com/erichstark/.

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