

Session 4.3

Estimation and Adaptive Control

Tuning an Adaptive Controller using a Robust Control Approach

J. Huebsch and H. Budman
University of Waterloo

Parameter Convergence in Adaptive Extremum Seeking Control

V. Adetola and M. Guay
Queen's University

Geometric Estimation of Ternary Distillation Columns

A. Pulis, C. Fernandez, R. Baratti, and J. Alvarez
Universidad Autonoma Metropolitana-Iztapalapa

Finite Time Observer for Nonlinear Systems

F. Sauvage, M. Guay and D. Dochain
Queen's University
Universite Catholique de Louvain

Dynamic Estimation and Uncertainty Quantification for Model-Based Control of Discrete Systems

J. Gândara, B. Duarte and N. M. C. Oliveira
Universidade de Coimbra

