Simple positive feedback COVID model

Positive feedback model with L = R g(s) November 2020 21 Dec. 2020

POSITIVE FEEDBACK MODEL



Key parameter:

- R reproductive number
- With herd immunity
 - $R(N) = R_0 (1 N/N_{pop})$
- R should be less than 1 for stability

Example of dynamics

- $g(s) = 1/(\tau_1 s + 1)$
- $g(s) = 1/(\tau_1 s+1)(\tau_2 s+1)$
- $g(s) = exp(-\theta s)/(\tau_1 s+1)$

N0 = number of initial cases (persons)
N = number of total cases
R = no. infected from one person
g(s) : dynamics for each person, assumed equal

Response: N = S(s) NO where S(s) = 1/(1-L) and L=R g(s)

For first-order dynamics, g(s) = 1/(tau1*s+1), S(s) = 1-k/(tau*s-1), k=R/(R-1), tau=tau1/(R-1). Resulting cases N for step in NO: N = (NO/(R-1))*(R*exp(rt)-1), where r = (R-1)/tau1

Note that this not quite on the form $N = k^* exp(rt)$, except when rt is large.

Is this simple positive feedback model really correct?

Sum Generations model



N0 = number of initial cases (persons)

- N = number of total cases
- R = no. infected from one person

g(s) : dynamics for each person, assumed equal

«Numerical proof» of Positive feedback model. Compare with sum of generations model



R=1.2; T0=100; G = 1/(6*s+1);L = R*G;

STEP RESPONSE for NO

% positive feedback model:

T=L*T0/(1-L); Tnew=s*T/(0.001*s+1); tt=60; figure(1); step(Tnew,tt,'red'); figure(2); step(T,tt,'red') % sum generations modcel:

T=0;

for n=1:15 % could only go to n=15 for numerical reasons

TT(n) = L^n*T0; % n = generation number

T = TT(n)+T;

end

Tnew=s*T/(0.001*s+1); figure(1); step(Tnew,tt); figure(2); step(T,tt)

Mathematical proof. Converging geometric series:

 $1+L+L^2+L^3+....=1/(1-L)$

The positive feedback model is clearly a simplification, since each person has their own dynamics g(s). So the full model is high-order, but the response is equal to the low-order positive feedback model



R=1.2, sum_i tau_i = 6, N0=100 Upper: First-order, tau=6 Middle: Second-order, tau1=tau2=6 Lower: With delay, theta=3, tau=3

Conclusion

- Very simple positive feedback model
- Can easily include any dynamics, g(s)
- I looked around, but I did not easily find such a simple model in the literature
- Feedback control by government: Adjust regulations to keep R below 1, maybe setpoint around 0.7 to avoid too much restrictions

