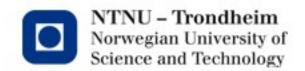
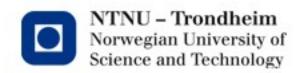
Optimal operation of energy storage in buildings: The use of hot water system

Emma Johansson
Supervisors: Sigurd Skogestad and Vinicius de Oliveira



Agenda

- Project description
- Work done
- Model validation
- Further work



Project description

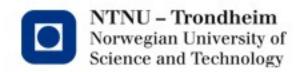
- Optimal operation of energy storage in buildings with focus on the optimization of an electrical water heating system.
- Objective is to minimize the energy cost of heating the water
- Main complications: Electricity price and future demand
- Goal: To propose, implement and compare different simple policies that result in near-optimal operation of the system.

 NTNU - Trondheim
 Norwegian University of

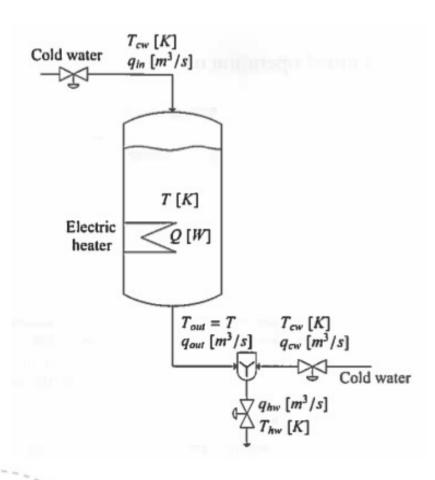
Science and Technology

Proposed policies

- Should be robust in some to-be-defines sense (e.g. must be feasible for at least 95% of the cases)
- Should result in significant savings compared to trivial solution
- Should be simple to implement in practice.



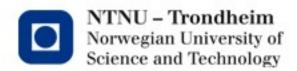
Process flow scheme



Dynamic model:

$$\frac{dV}{dt} = q_{in} - q_{out}$$

$$\frac{dT}{dt} = \frac{1}{V}[q_{in}(T_{in} - T) + \frac{Q}{\rho c_p}]$$

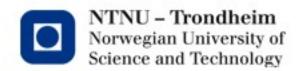


Model assumptions

- qhw and Thws controlled directly by the consumer
- Perfect control when feasible

Perfect control:
$$T_{hw} = T_{hw,s}$$
 and $q_{hw} = q_{hw,s}$

else
$$T < T_{hw,s}$$
 and $q_{hw} = q_{hw,s}$

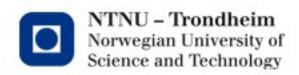


Model equation

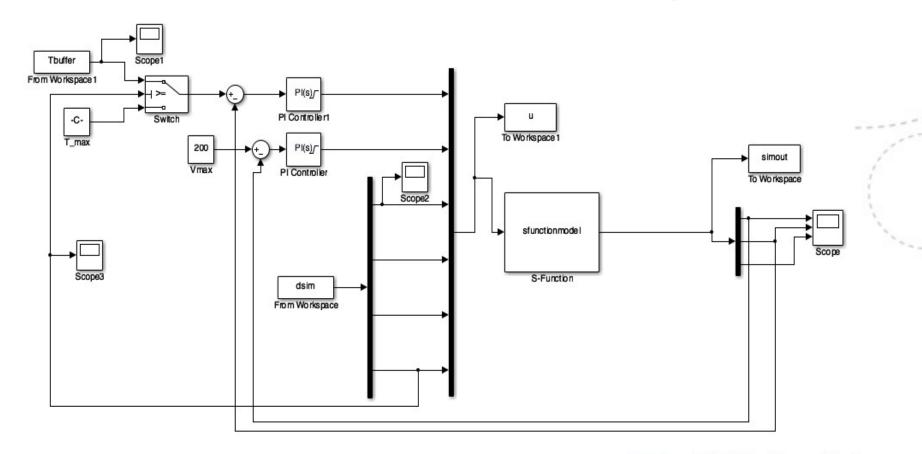
$$rac{dx}{dt} = f(x, u, d)$$

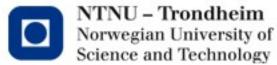
Definition of the state, input and disturbance vectors.

$$x = egin{bmatrix} V \ T \end{bmatrix}, u = egin{bmatrix} Q \ q_{in} \end{bmatrix}, d = egin{bmatrix} q_{hw} \ T_{hw,s} \ T_{in} \ p \end{bmatrix}$$



Model validation

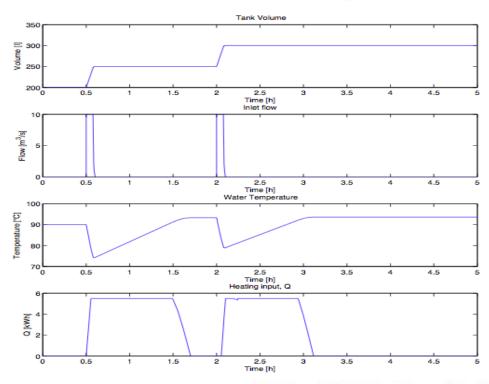




PID controller

$$p(t) = p + K_c(e(t) + \frac{1}{\tau_I} \int_0^t e(t*) dt + \tau_D \frac{de(t)}{dt})$$

$$G(s) = K_p(1 + rac{1}{ au_I s} + au_D s)$$

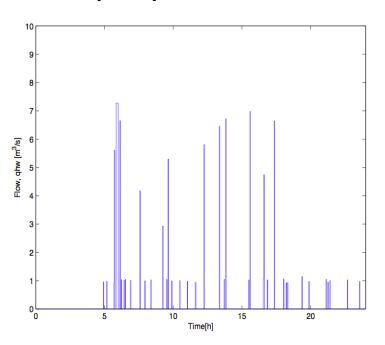


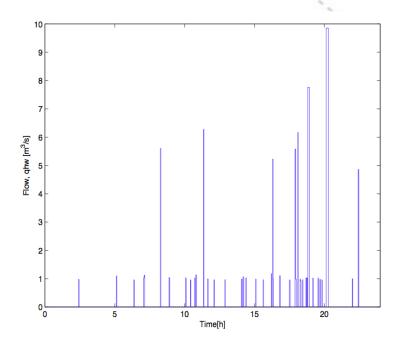


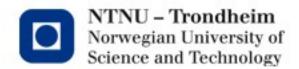
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Demand profile

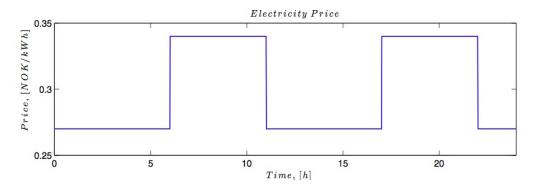
Randomly generated demand profiles from MATLAB script, qhw.

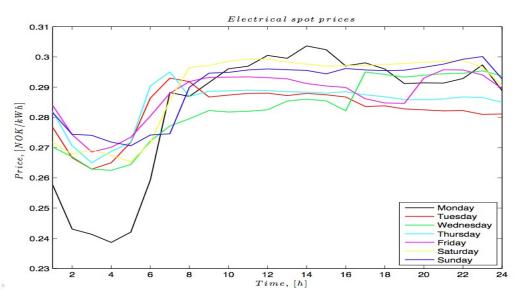






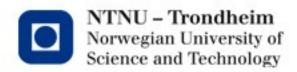
Electricity Price



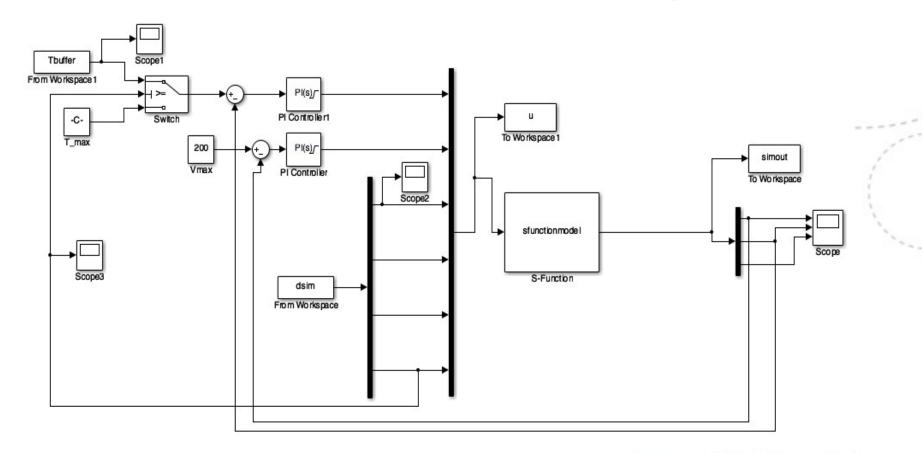


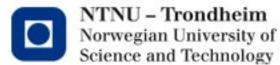
 On-off peak price

Time varying price



Implementing a switch

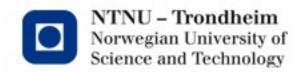




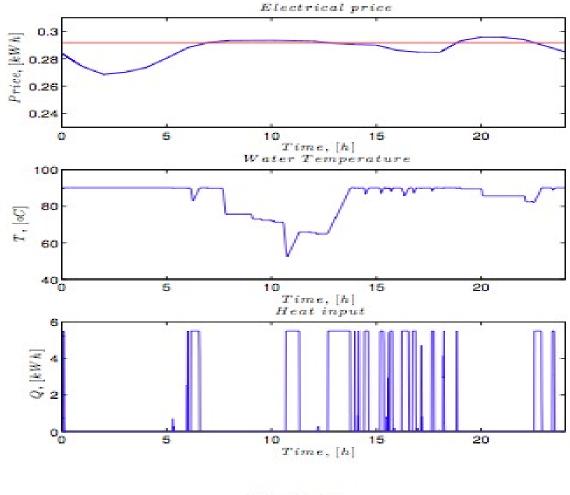
Price threshold, p_B

Defining set-points for the temperature at the switch

$$T_{set} = egin{cases} ext{if } p > p_B ext{ then } T_{set} = T_{max} \ ext{if } p \leq p_B ext{ then } T_{set} = T_{buffer} \ \end{cases}$$
 $T_{set} = egin{cases} ext{if } p > p_B ext{ then } V_{set} = V_{max} \ ext{if } p \leq p_B ext{ then } V_{set} = V_{max} \end{cases}$

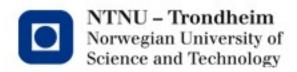


Results

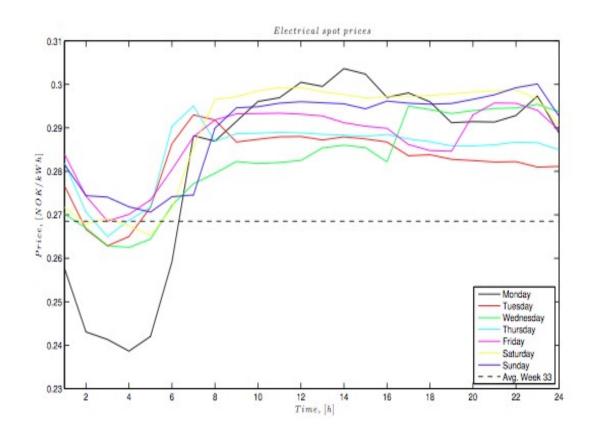


 Switching between set-points as the price is higher or lower than the price threshold P_B.

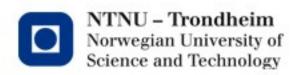
(b) Friday



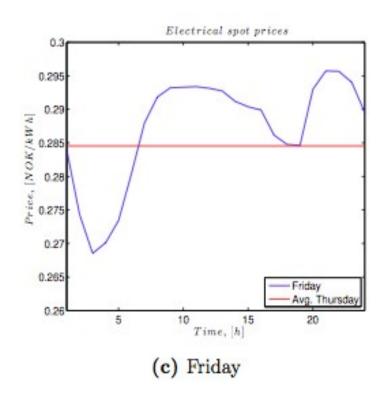
Weekly average

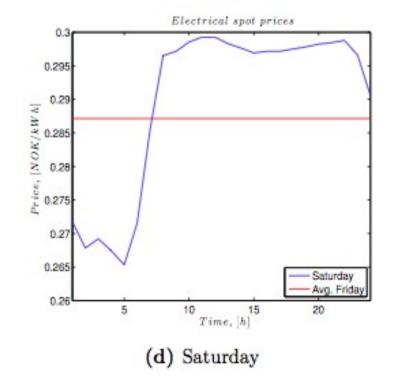


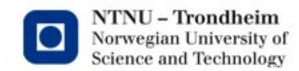
PB average from previous week



Average from previous day

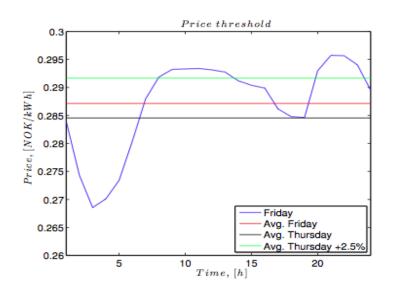


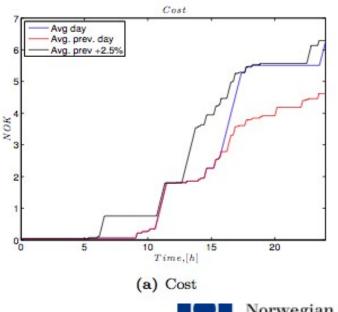




Average current day

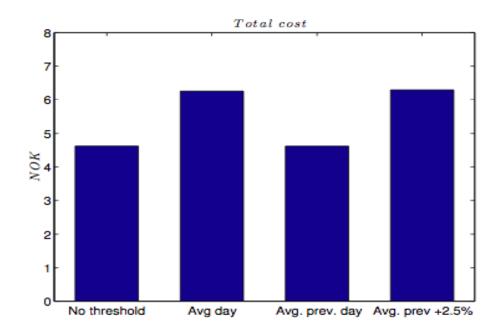
 Comparing the total cost with different boundaries, also assuming the electricity price for the current day is known, and the average of this day can be used.

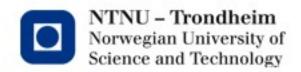




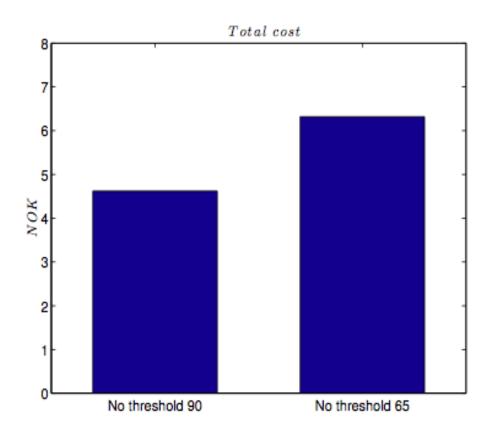
No boundary?

 The lowest price threshold resulted in the lowest cos, what are the result with no boundary?

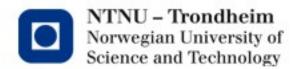




No boundary?



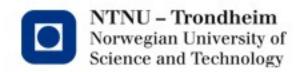
- T_{start} = 90 °C, low total cost.
- T_{start} = 65 °C, higher total cost.



Cost function

- Original cost function: $J(t) = \int_0^t p(t)Q(t)dt$
- Implementing a penalty into the cost function:

$$\begin{split} J &= \int\limits_{t_0}^{\infty} p(t)Q\mathrm{d}t + \int\limits_{t_0}^{\infty} p*(T)Q_{demand}\mathrm{d}t \\ p*(T) &= \begin{cases} 0 & \text{if } T \geq T_{hw,s} \\ p_1*(T_{hw,s}-T)^2 + p_2*(T_{hw,s}-T) & \text{if } T < T_{hw,s} \end{cases} \end{split}$$



Further work

- Optimization problem: min J(PB, Tbuffer)
 - Decision variables: PB and Tbuffer

Finding the optimal PB and Tbuffer which provides the lowest total cost.

Simulate for longer periodes and generalizing the simulation

Find near optimal policies

